

Objectification — from functional to state-based models

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Functional modeling

Consider the following model of a *stack*:

- Datatype:

$$\text{Stack } A \triangleq A^*$$

- Functionality

$$\text{empty} : \text{Stack } A \rightarrow \mathbb{B}$$

$$\text{empty } s \triangleq s = []$$

$$\text{push} : A \rightarrow \text{Stack } A \rightarrow \text{Stack } A$$

$$\text{push } a \ s \triangleq a : s$$

$$\text{Pop} : \text{Stack } A \rightarrow \text{Stack } A$$

$$\text{Pop } s \triangleq \text{tail } s$$

$$\text{pre } \neg(\text{empty } s)$$

$$\text{Top} : \text{Stack } A \rightarrow A$$

$$\text{Top } s \triangleq \text{head } s$$

$$\text{pre } \neg(\text{empty } s)$$

$$\text{clear} : \text{Stack } A \rightarrow \text{Stack } A$$

$$\text{clear } s \triangleq []$$

Questions

- Is this the *only* way to specify a stack?
- Compare with, at programming level
 - functional program (eg. in Haskell)
 - imperative program (eg. in C)
 - object oriented program (eg. in Java)
- How do we *bridge the gap* between such an abstract model and other models closer to such programming languages?

Objectification

- Process of inferring object class models from a purely functional models
- Based on Coad and Yourdon's principle:
The potential class must have a set of identifiable operations that can change the value of its attributes in some way. [1]
- One needs to identify what Coad and Yourdon mean by **attributes**
- More generally, one needs to identify the **state** space of an **automaton**

About automata

Given a set A (input alphabet), a set B (output alphabet) and a set of states S , a Deterministic Mealy Machine (DMM) is specified by a transition function of type

$$\delta : A \rightarrow (S \rightarrow (B \times S))$$

Whenever $(b, s') = \delta a s$, we say that there is a transition

$$s' \xleftarrow{a|b} s$$

and refer to s as the **before** state, and to s' as the **after** state.

First step: identify the DMM

Analysis of functionality of example given shows:

- All involve either an argument or result of type *Stack A*
- There is at least one function where *Stack A* is the type of both an argument and the result (two in fact: *push* and *Pop*.)
- Easy to see that eg.

$$\mathit{push} : A \rightarrow (\mathit{Stack} A \rightarrow (1 \times \mathit{Stack} A))$$

is itself a **DMM** (note the **1** signaling the *empty* output)
whose **state** is of type *Stack A*

- Other functionality can be converted into DMMs by adding **1**s where needed, eg.

$$\mathit{clear} : 1 \rightarrow (\mathit{Stack} A \rightarrow (1 \times \mathit{Stack} A))$$

(note the *empty* input this time)

First step: identify the DMM

- Other functionality can be converted into DMMs by explicitly declaring that the state doesn't change, eg.

$$Top : 1 \rightarrow (Stack\ A \rightarrow (A \times Stack\ A))$$

$$Top\ _ s \triangleq (head\ s, s)$$

$$pre\ \neg(empty\ s)$$

Altogether

- we can build an **object** as a composite DMM which encompasses the whole functionality,
- whose **state** is of type *Stack A* and where
- push*, *Pop* and *clear* modify the state (they **w**rite on it)
- Top* and *empty* read (abbrev. **rd**) the state only

Comments

- Building the DMM as above is the right (formal) way but involves a number of technical details [2] which it is wise to ignore for the time being
- Below we head for a *practical* method based on **pre/post**-conditions
- So we go for implicit specifications

Second step: go implicit

empty : ($s : \text{Stack } A$) \rightarrow ($r : \mathbb{B}$)

post $r = (s = [])$

push : ($a : A$) \rightarrow ($s : \text{Stack } A$) \rightarrow ($r : \text{Stack } A$)

post $r = a : s$

Pop : ($s : \text{Stack } A$) \rightarrow ($r : \text{Stack } A$)

pre $\neg(\text{empty } s)$

post $r = \text{tail } s$

Top : ($s : \text{Stack } A$) \rightarrow ($r : A$)

pre $\neg(\text{empty } s)$

post $r = \text{head } s$

clear : ($s : \text{Stack } A$) \rightarrow ($r : \text{Stack } A$)

post $r = []$

Third step: factor out state

A way to indicate that *Stack A* is the DMM's state is to drop this from the signatures while marking each operation as a state **reader** or state **writer**:

$empty : \rightarrow (r : \mathbb{B})$
rd $s : Stack\ A$

$Top : \rightarrow (r : A)$
rd $s : Stack\ A$

$push : (a : A) \rightarrow$
wr $s : Stack\ A$

$clear : \rightarrow$
wr $s : Stack\ A$

$Pop : \rightarrow$
wr $s : Stack\ A$

Notation: state readers

By writing

$$OP : (b : B) \leftarrow (a : A)$$

$$\mathbf{rd} \ s : St$$

$$\mathbf{pre} \ precond(s, a)$$

$$\mathbf{post} \ postcond(s', b, s, a)$$

we mean an operation which does not modify the state:

$$\mathbf{pre-}OP \quad : \quad St \times A \rightarrow \mathbb{B}$$

$$\mathbf{pre-}OP(s, a) \triangleq precond(s, a)$$

$$\mathbf{post-}OP \quad : \quad St \times B \times St \times A \rightarrow \mathbb{B}$$

$$\mathbf{post-}OP(s', b, s, a) \triangleq postcond(s', b, s, a) \wedge s' = s$$

Notation: state writers

By writing

$$OP : (b : B) \leftarrow (a : A)$$

$$\mathbf{wr} \ s : St$$

$$\mathbf{pre} \ \text{precond}(s, a)$$

$$\mathbf{post} \ \text{postcond}(s', b, s, a)$$

we mean

$$\text{pre-}OP \quad : \quad St \times A \rightarrow \mathbb{B}$$

$$\text{pre-}OP(s, a) \quad \triangleq \quad \text{precond}(s, a)$$

$$\text{post-}OP \quad : \quad St \times B \times St \times A \rightarrow \mathbb{B}$$

$$\text{post-}OP(s', b, s, a) \quad \triangleq \quad \text{postcond}(s', b, s, a)$$

that is, condition $s' = s$ is dropped.

Fourth step: merge and rename

Readers and writers can be combined so as to build a DMM whose transitions involve operations which both yield a result **and** modify the state:

EMPTY : $\rightarrow (b : \mathbb{B})$
rd $s : \text{Stack } A$
post $b = (\text{empty } s)$

PUSH : $(a : A) \rightarrow$
wr $s : \text{Stack } A$
post $s' = a : s$

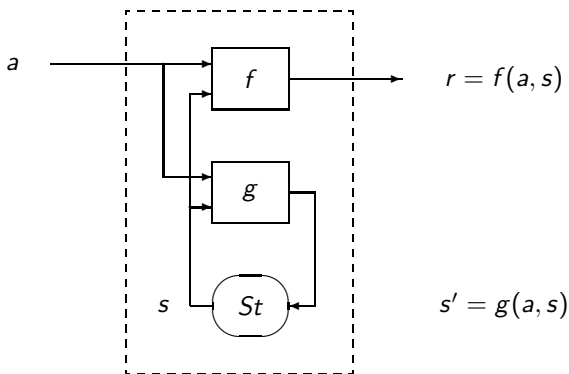
POP : $\rightarrow (r : A)$
wr $s : \text{Stack } A$
pre $\neg(\text{empty } s)$
post $s' = \text{tail } s \wedge r = \text{head } s$

TOP : $\text{Stack } A \rightarrow A$
rd $s : \text{Stack } A$
pre $\neg(\text{empty } s)$
post $r = \text{head } s$

CLEAR : \rightarrow
wr $s : \text{Stack } A$
post $s' = []$

Combining functions to build writers

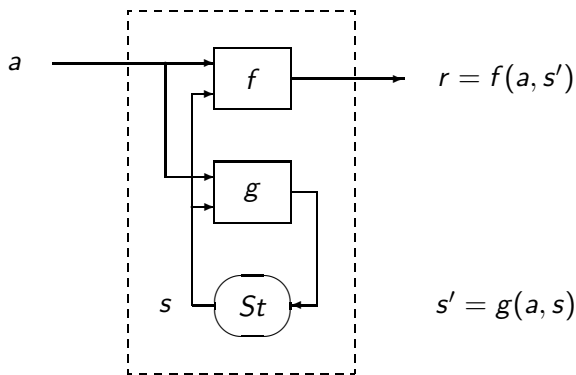
The “output first” pattern:



post $r = f(a, s) \wedge s' = g(a, s)$

Combining functions to build writers

The “update first” pattern:



post $s' = g(a, s) \wedge r = f(a, s')$

Example of *update first* writer

A cash-point operation:

DEBIT : $(m : \text{Amount}) \rightarrow (r : \text{Receipt})$

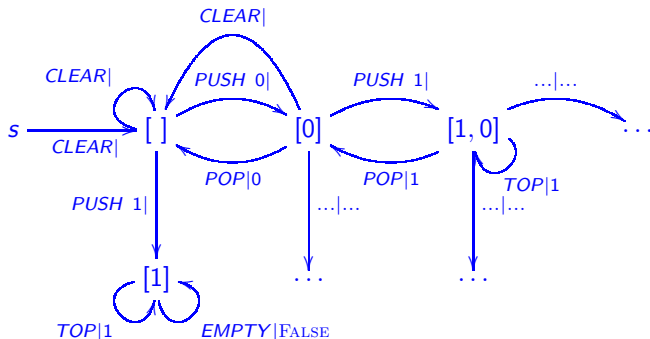
wr $s : \text{Account}$

pre $m \leq \text{balance } s$

post $s' = \text{debit } m \ s \ \wedge \ r = \text{balance } s'$

DMM semantics

- The behaviour of the *Stack* DMM is defined as the set of all state transitions which can take place as dictated by **pre/post**-condition pairs.
- Example: for $A = \{0, 1\}$, $B = A \cup \mathbb{B}$, the state transition diagram will include



etc

Behavioural safety and nondeterminism

Note that

- state transition diagram rules out all transitions whose before-states violate pre-conditions
- in general, there may exist operations such as eg.

Pick $:\rightarrow (x : \text{Marble})$

wr $b : \text{Bag}$

pre $b \neq \{\}$

post $x \in b \wedge b' = b - \{x\}$

So, in general, Mealy machines can be nondeterministic.

Proof obligation

For every

$OP : (b : B) \leftarrow (a : A)$

wr/rd $s : St$

pre ...

post ...

where St , A and B are subject to invariants, one is obliged to discharge the following proof:

Satisfiability

$$\left\langle \begin{array}{l} \forall s, a : \\ s \in St \wedge a \in A : \\ \text{pre-}OP(s, a) \Rightarrow \langle \exists s', b : s' \in St \wedge b \in B : \text{post-}OP(s', b, s, a) \rangle \end{array} \right\rangle$$

Back to functions

DMMs can be built and animated using the state monad:

- Recall

$$\delta : A \rightarrow \underbrace{(S \rightarrow (B \times S))}_{ST \ S \ B}$$

- Every function of type $ST \ S \ B$ will be referred to as a **state transformer**
- For a fixed state space S , $F \stackrel{\text{def}}{=} ST \ S$ can be turned into a **monad**
- Split* combinator $\langle f, g \rangle a \triangleq (f \ a, g \ a)$ useful in building state transformers

Building state transformers

Update state:

$$\text{update} : (S \rightarrow S) \rightarrow ST\ S\ 1$$

$$\text{update } f \triangleq \langle !, f \rangle$$

Query the state:

$$\text{query} : (S \rightarrow B) \rightarrow ST\ S\ B$$

$$\text{query } f \triangleq \langle f, id \rangle$$

Return a result:

$$\text{return} : B \rightarrow ST\ S\ B$$

$$\text{return } b \triangleq \langle \underline{b}, id \rangle$$

Combining state transformers

Sequential composition:

$$seq : ST\ S\ A \rightarrow ST\ S\ B \rightarrow ST\ S\ B$$

$$seq\ f\ g \triangleq do\ \{f; g\}$$

"Update first" transformer:

$$updfst : (A \rightarrow S \rightarrow S) \rightarrow (A \rightarrow S \rightarrow B) \rightarrow A \rightarrow ST\ S\ B$$

$$updfst\ g\ f\ a \triangleq do\ \{update(g\ a); query(f\ a)\}$$

"Query first" transformer:

$$qryfst : (A \rightarrow S \rightarrow S) \rightarrow (A \rightarrow S \rightarrow B) \rightarrow A \rightarrow ST\ S\ B$$

$$qryfst\ g\ f\ a \triangleq do\ \{b \leftarrow query(f\ a); update(g\ a); return\ b\}$$

Animating state transformers

Running:

$$\begin{aligned} \text{run} &: ST\ S\ A \rightarrow S \rightarrow (A \times S) \\ \text{run } g\ s &\triangleq g\ s \end{aligned}$$

Example: given $POP \triangleq \text{qryfst head tail}$, by running POP over state $[1, 2, 3]$ one obtains

$$\text{run } POP\ [1, 2, 3] = (1, [2, 3])$$

This **reactive** behaviour can only be animated for DMMs. Nondeterminism requires explicit use of test suites guided by post-conditions.



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