# Transposing Relations: From Maybe Functions to Hash Tables 

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#### Abstract

Functional transposition is a technique for converting relations into functions aimed at developing the relational algebra via the algebra of functions. This paper attempts to develop a basis for generic transposition. Two instances of this construction are considered, one applicable to any relation and the other applicable to simple relations only. Our illustration of the usefulness of the generic transpose takes advantage of the free theorem of a polymorphic function. We show how to derive laws of relational combinators as free theorems of their transposes. Finally, we relate the topic of functional transposition with the hashing technique for efficient data representation.


## 1 Introduction

This paper is concerned with techniques for functional transposition of binary relations. By functional transposition we mean the faithful representation of a relation by a (total) function. But - what is the purpose of such a representation?

Functions are well-known in mathematics and computer science because of their rich theory. For instance, they can be dualized (as happens e.g. with the projection/injection functions), they can be Galois connected (as happens e.g. with inverse functions) and they can be parametrically polymorphic. In the latter case, they exhibit theorems "for free" [20] which can be inferred solely by inspection of their types.

However, (total) functions are not enough. In many situations, functions are partial in the sense that they are undefined for some of their input data. Programmers have learned to deal with this situation by enriching the codomain of such functions with a special error mark indicating that nothing is output. In C/C++, for instance, this leads to functions which output pointers to values rather than just values. In functional languages such as Haskell [13], this leads to functions which output Maybe-values rather than values, where Maybe is datatype Maybe $a=$ Nothing $\mid$ Just $a$.

Partial functions are still not enough because one very often wants to describe what is required of a function rather than prescribe how the function should compute its result. A well-known example is sorting: sorting a list amounts to finding an ordered permutation of the list independently of the particular sorting algorithm eventually chosen to perform the task (eg. quicksort, mergesort, etc.). So one is concerned not only with implementations but also with specifications, which can be vague (eg. which square root is meant when one writes " $\sqrt{x}$ "?) and non-deterministic. Functional programmers have
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learned to cope with (bounded) non-determinism by structuring the codomain of such functions as sets or lists of values.

In general, such powerset valued functions are models of binary relations: for each such $f$ one may define the binary relation $R$ such that $b R a$ means $b \in(f a)$ for all suitably typed $a$ and $b$. Such $R$ is unique for the given $f$. Conversely, any binary relation $R$ is uniquely transposed into a set-valued function $f$. The existence and uniqueness of such a transformation leads to the identification of a transpose operator $\Lambda$ [6] satisfying the following universal property,

$$
\begin{equation*}
f=\Lambda R \equiv(b R a \equiv b \in f a) \tag{1}
\end{equation*}
$$

for all $R$ from $A$ to $B$ and $f: A \longrightarrow \mathcal{P} B \cdot(\mathcal{P} B$ denotes the set of all subsets of $B$.)
The power-transpose operator $\Lambda$ establishes a well-known isomorphism between relations and set-valued functions which is often exploited in the algebra of relations, see for instance textbook [6]. Less popular and usually not identified as a transpose is the conversion of a partial function into a Maybe-valued function, for which one can identify, by analogy with (1), isomorphism $\Gamma$ defined by (for all suitably typed $a$ and $b$ )

$$
\begin{equation*}
f=\Gamma R \equiv(b R a \equiv(f a=\text { Just } b)) \tag{2}
\end{equation*}
$$

where $R$ ranges over partial functions.
Terms total and partial are avoided in relation algebra because they clash with a different meaning in the context of partial orders and total orders, which are other special cases of relations. Instead, one writes entire for total, and simple relation is written instead of partial function. The word function is reserved for total, simple relations which find a central place in the taxonomy of binary relations depicted in Fig. 1 (all other entries in the taxonomy will be explained later on).

Paper objectives. This paper is built around three main topics. First, we want to show that $\Lambda$ is not the only operator for transposing relations. It certainly is the most general, but we will identify other such operators as we go down the hierarchy of binary relations. Our main contribution will be to unify such operators under a single, generic transpose construct based on the notion of generic membership which extends " $\epsilon$ " to collective types other than the powerset $[6,10,11]$. In particular, one of these operators will be related with the technique of representing finite data collections by hash-tables, which are efficient data-structures well-known in computer science [21,12].

Second, we want to stress on the usefulness of transposing relations by exploiting the calculation power of functions, namely free theorems. Such powerful reasoning devices can be applied to relations provided we represent relations as functions (by functional transposition), reason functionally and come back to relations where appropriate. In fact, several relational combinators studied in [6] arise from the definition of the power-transpose $\Lambda R$ of a relation $R$. However, some results could have been produced as free-theorems, as we will show in the sequel.

Last but not least, we want to provide evidence of the practicality of the pointfree relation calculus. The fact that pointfree notation abstracts from "points" or variables makes the reasoning more compact and effective, as is apparent in our final example on hash-tables, if compared with its pointwise counterpart which one of the authors did several years ago [16].


Fig. 1. Binary relation taxonomy

Related work. In the literature, equations (1) and (2) have been dealt with in disparate contexts. While (1) is adopted as "the" standard transpose in [6], for instance, (2) is studied in [9] as an example of an adjunction between the categories of total and partial functions. From the literature on the related topic of generic membership we select [6] and [11].

Paper structure. This paper is structured as follows. In the next section we present an overview of (pointfree) relation algebra. Section 3 presents our relational study of generic transpose. In section 4, the two transposes (1) and (2) are framed in the generic view. Section 5 presents an example of reasoning based on the generic transpose operator and its instances. In the remainder of the paper we relate the topic of functional transposition with the hash table technique for data representation and draw some conclusions which lead to plans for future work.

## 2 Overview of the Relational Calculus

Relations. Let $B \stackrel{R}{\longleftarrow} A$ denote a binary relation on datatypes $A$ (source) and $B$ (target). We write $b R a$ to mean that pair $(b, a)$ is in $R$. The underlying partial order on relations will be written $R \subseteq S$, meaning that $S$ is either more defined or less deterministic than $R$, that is, $R \subseteq S \equiv b R a \Rightarrow b S a$ for all $a, b . R \cup S$ denotes the union of two relations and $\top$ is the largest relation of its type. Its dual is $\perp$, the smallest such relation. Equality on relations can be established by $\subseteq$-antisymmetry: $R=S \equiv$ $R \subseteq S \wedge S \subseteq R$.

Relations can be combined by three basic operators: composition $(R \cdot S)$, converse $\left(R^{\circ}\right)$ and meet $(R \cap S)$. $R^{\circ}$ is the relation such that $a\left(R^{\circ}\right) b$ iff $b R a$ holds. Meet corresponds to set-theoretical intersection and composition is defined in the usual way: $b(R \cdot S) c$ holds wherever there exists some mediating $a \in A$ such that $b R a \wedge a S c$. Everywhere $T=R \cdot S$ holds, the replacement of $T$ by $R \cdot S$ will be referred to as a "factorization" and that of $R \cdot S$ by $T$ as "fusion". Every relation $B \leftarrow^{R} A$ admits
two trivial factorizations, $R=R \cdot i d_{A}$ and $R=i d_{B} \cdot R$ where, for every $X, i d_{X}$ is the identity relation mapping every element of $X$ onto itself.

Coreflexives. Some standard terminology arises from the id relation: a (endo)relation $A \not{ }^{R} A$ (often called an order) will be referred to as reflexive iff $i d_{A} \subseteq R$ holds and as coreflexive iff $R \subseteq i d_{A}$ holds. As a rule, subscripts are dropped wherever types are implicit or easy to infer.

Coreflexive relations are fragments of the identity relation which can be used to model predicates or sets. The meaning of a predicate $p$ is the coreflexive $\llbracket p \rrbracket$ such that $b \llbracket p \rrbracket a \equiv(b=a) \wedge(p a)$, that is, the relation that maps every $a$ which satisfies $p$ (and only such $a$ ) onto itself. The meaning of a set $S \subseteq A$ is $\llbracket \lambda a . a \in S \rrbracket$, that is, $b \llbracket S \rrbracket a \equiv(b=a) \wedge a \in S$. Wherever clear from the context, we will omit the $\llbracket \rrbracket$ brackets.

Orders. Preorders are reflexive, transitive relations, where $R$ is transitive iff $R \cdot R \subseteq R$ holds. Partial orders are anti-symmetric preorders, where $R$ is anti-symmetric wherever $R \cap R^{\circ} \subseteq i d$ holds. A preorder $R$ is an equivalence if it is symmetric, that is, if $R=R^{\circ}$.

Converse is of paramount importance in establishing a wider taxonomy of binary relations. Let us first define the kernel of a relation, ker $R=R^{\circ} \cdot R$ and its dual, $\operatorname{img} R=\operatorname{ker}\left(R^{\circ}\right)$, called the image of $R$. Alternatively, we may define $\operatorname{img} R=$ $R \cdot R^{\circ}$, since converse commutes with composition, $(R \cdot S)^{\circ}=S^{\circ} \cdot R^{\circ}$ and is involutive, that is, $\left(R^{\circ}\right)^{\circ}=R$. Kernel and image lead to the following terminology: a relation $R$ is said to be entire (or total) iff its kernel is reflexive; or simple (or functional) iff its image is coreflexive. Dually, $R$ is surjective iff $R^{\circ}$ is entire, and $R$ is injective iff $R^{\circ}$ is simple. This terminology is recorded in the following summary table:

|  | Reflexive | Coreflexive |
| :--- | :---: | :---: |
| ker $R$ | entire $R$ | injective $R$ |
| $i m g R$ | surjective $R$ | simple $R$ |

Functions. A relation is a function iff it is both simple and entire. Functions will be denoted by lowercase letters ( $f, g$, etc.) and are such that $b f a$ means $b=f a$. Function converses enjoy a number of properties of which the following is singled out because of its rôle in pointwise-pointfree conversion [3] :

$$
\begin{equation*}
b\left(f^{\circ} \cdot R \cdot g\right) a \equiv(f b) R(g a) \tag{4}
\end{equation*}
$$

The overall taxonomy of binary relations is pictured in Fig. 1 where, further to the standard classification, we add representations and abstractions. These are classes of relations useful in data-refinement [15]. Because of $\subseteq$-antisymmetry, img $S=i d$ wherever $S$ is an abstraction and ker $R=i d$ wherever $R$ is a representation. This ensures that "no confusion" arises in a representation and that all abstract data are reachable by an abstraction ("no junk").

Isomorphisms (such as $\Lambda$ and $\Gamma$ above) are functions, abstractions and representations at the same time. A particular isomorphism is id, which also is the smallest equivalence relation on a particular data domain. So, $b$ id $a$ means the same as $b=a$.

Functions and relations. The interplay between functions and relations is a rich part of the binary relation calculus. This arises when one relates the arguments and results of pairs of functions $f$ and $g$ in, essentially, two ways:

$$
\begin{align*}
f \cdot S & \subseteq R \cdot g  \tag{5}\\
f^{\circ} \cdot S & =R \cdot g \tag{6}
\end{align*}
$$

As we shall see shortly, (5) is equivalent to $S \subseteq f^{\circ} \cdot R \cdot g$ which, by (4), means that $f$ and $g$ produce $R$-related outputs $f b$ and $g a$ provided their inputs are $S$-related ( $b S a$ ). This situation is so frequent that one says that, everywhere $f$ and $g$ are such that (5) holds, $f$ is $(R \leftarrow S)$-related to $g$ :

For instance, for partial orders $R, S:=\leq, \sqsubseteq$, fact $f(\leq \leftarrow \sqsubseteq) f$ means that $f$ is monotone. For $R, S:=\leq, i d$, fact $f(\leq \leftarrow i d) g$ means

$$
\begin{equation*}
f \leq g \equiv f \subseteq \leq \cdot g \tag{8}
\end{equation*}
$$

that is, $f$ and $g$ are such that $f b \leq g b$ for all $b$. Therefore, $\leq$ lifts pointwise ordering $\leq$ to the functional level. In general, relation $R \leftarrow S$ will be referred to as "Reynolds arrow combinator" (see section 5), which is extensively studied in [3].

Concerning the other way to combine relations with functions, equality (6) becomes interesting wherever $R$ and $S$ are preorders,

$$
\begin{equation*}
f^{\circ} \cdot \sqsubseteq=\leq \cdot g \text { cf. diagram: } \bigcap_{B \underset{g}{\leftrightarrows}}^{\text {¢ }} C^{\sqsubseteq} \tag{9}
\end{equation*}
$$

in which case $f, g$ are always monotone and said to be Galois connected. Function $f$ (resp. $g$ ) is referred to as the lower (resp. upper) adjoint of the connection. By introducing variables in both sides of (9) via (4) we obtain

$$
\begin{equation*}
(f b) \sqsubseteq a \equiv b \leq(g a) \tag{10}
\end{equation*}
$$

Note that (9) boils down to $f^{\circ}=g$ (ie. $f=g^{\circ}$ ) wherever $\leq$ and $\sqsubseteq$ are $i d$, in which case $f$ and $g$ are isomorphisms, that is, $f^{\circ}$ is also a function and $f b=a \equiv b=f^{\circ} a$ holds.

For further details on the rich theory of Galois connections and examples of application see $[1,3]$. Galois connections in which the two preorders are relation inclusion ( $\leq, \sqsubseteq:=\subseteq, \subseteq$ ) are particularly interesting because the two adjoints are relational combinators and the connection itself is their universal property. The following table lists connections which are relevant for this paper:

| $(f X) \subseteq Y \equiv X \subseteq(g Y)$ |  |  |  |
| :---: | :---: | :---: | :---: |
| Description | $f$ | $g$ | Obs. |
| Converse | $(-)^{\circ}$ | $(-)^{\circ}$ |  |
| Shunting rule | $(f \cdot)$ | $\left(f^{\circ} \cdot\right)$ | NB: $f$ is a function |
| "Converse" shunting rule | $\left(\cdot f^{\circ}\right)$ | $(\cdot f)$ | NB: $f$ is a function |
| Left-division | $(R \cdot)$ | $(R \backslash)$ | read " $R$ under $\ldots$ " |
| Right-division | $(\cdot R)$ | $(/ R)$ | read " $\ldots$ over $R$ " |
| Difference | $(--R)$ | $(R \cup)$ |  |

From the two of these called shunting rules one infers the very useful fact that equating functions is the same as comparing them in either way:

$$
\begin{equation*}
f=g \equiv f \subseteq g \equiv g \subseteq f \tag{12}
\end{equation*}
$$

Membership. Equation (1) involves the set-theoretic membership relation $A \longleftarrow{ }_{\longleftarrow}^{\epsilon} \mathcal{P} A$. Sentence $a \in x$ (meaning that " $a$ belongs to $x$ " or " $a$ occurs in $x$ ") can be generalized to $x$ 's other than sets. For instance, one may check whether a particular integer occurs in one or more leaves of a binary tree, or of any other collective or container type $F$.

Such a generic membership relation will have type $A \stackrel{\epsilon}{\leftrightarrows} A$, where F is a type parametric on $A$. Technically, the parametricity of F is captured by regarding it as a relator [5], a concept which extends functors to relations: $\mathrm{F} A$ describes a parametric type while $\mathrm{F} R$ is a relation from $\mathrm{F} A$ to $\mathrm{F} B$ provided $R$ is a relation from $A$ to $B$. Relators are monotone and commute with composition, converse and the identity.

The most simple relators are the identity relator Id, which is such that Id $A=A$ and Id $R=R$, and the constant relator K (for a particular concrete data type $K$ ) which is such that $\mathrm{K} A=K$ and $\mathrm{K} R=i d_{K}$.

Relators can also be multi-parametric. Two well-known examples of binary relators are product and sum,

$$
\begin{align*}
& R \times S=\left\langle R \cdot \pi_{1}, S \cdot \pi_{2}\right\rangle  \tag{13}\\
& R+S=\left[i_{1} \cdot R, i_{2} \cdot S\right] \tag{14}
\end{align*}
$$

where $\pi_{1}, \pi_{2}$ denote the projection functions of a Cartesian product, $i_{1}, i_{2}$ denote the injection functions of a disjoint union, and the split/either relational combinators are defined by

$$
\begin{align*}
\langle R, S\rangle & =\pi_{1}^{\circ} \cdot R \cap \pi_{2}^{\circ} \cdot S  \tag{15}\\
{[R, S] } & =\left(R \cdot i_{1}^{\circ}\right) \cup\left(S \cdot i_{2}^{\circ}\right) \tag{16}
\end{align*}
$$

By putting these four kinds of relator (product, sum, identity and constant) together with fixpoint definition one is able to specify a large class of parametric structures called polynomial - such as those implementable in Haskell. For instance, the Maybe
datatype is an implementation of polynomial relator $\mathrm{F}=\mathrm{Id}+1$ (ie. $\mathrm{F} A=A+1$ ), where 1 denotes the singleton datatype, written () in Haskell.

There is more than one way to generalize $A \longleftarrow \mathcal{P} A$ to relators other than the powerset. (For a thorough presentation of the subject see chapter 4 of [10].) For the purpose of this paper it will be enough to say that $A \stackrel{\epsilon_{\mathrm{F}}}{\leftrightarrows} \mathrm{F} A$, if it exists, is a lax natural transformation [6], that is,

$$
\begin{equation*}
\epsilon_{\mathrm{F}} \cdot \mathrm{~F} R \subseteq R \cdot \epsilon_{\mathrm{F}} \tag{17}
\end{equation*}
$$

holds. Moreover, relators involving,$+ \times$, Id and constants have membership defined inductively as follows:

$$
\begin{align*}
\epsilon_{\mathrm{K}} & \stackrel{\text { def }}{=} \perp  \tag{18}\\
& \epsilon_{\mathrm{Id}} \stackrel{ }{=} \stackrel{\text { def }}{=} i d  \tag{19}\\
\epsilon_{\mathrm{F} \times \mathrm{G}} & \stackrel{\text { def }}{=}\left(\epsilon_{\mathrm{F}} \cdot \pi_{1}\right) \cup\left(\epsilon_{\mathrm{G}} \cdot \pi_{2}\right)  \tag{20}\\
\epsilon_{\mathrm{F}+\mathrm{G}} & \stackrel{\text { def }}{=}\left[\epsilon_{\mathrm{F}}, \epsilon_{\mathrm{G}}\right] \tag{21}
\end{align*}
$$

## 3 A Study of Generic Transposition

Thanks to rule (4), it is easy to remove variables $b$ and $a$ from transposition rules (1) and (2), yielding

$$
\begin{align*}
& f=\Lambda R \equiv(R=\epsilon \cdot f)  \tag{22}\\
& f=\Gamma R \equiv\left(R=i_{1}^{\circ} \cdot f\right) \tag{23}
\end{align*}
$$

where, in the second equivalence, $R$ ranges over simple relations and Just is replaced by injection $i_{1}$ associated with relator Id +1 . In turn, $f$ and $R$ can also be abstracted from $(22,23)$ using the same rule, whereby we end up with $\Lambda=(\epsilon \cdot)^{\circ}$ and $\Gamma=\left(i_{1}^{\circ} \cdot\right)^{\circ}$.

The generalization of both equations starts from the observation that, in the same way $\in$ is the membership relation associated with the powerset, $i_{1}^{\circ}$ is the membership relation associated with $\mathrm{Id}+1$, as can be easily checked:

$$
\begin{align*}
& \epsilon_{\mathrm{ld}+1} \\
= & \{\text { by }(21)\} \\
= & \left\{\epsilon_{\mathrm{Id}}, \epsilon_{1}\right] \\
= & \{\text { by }(19) \text { and }(18)\} \\
= & \{\text { by }(16), \perp]  \tag{24}\\
= & i d \cdot i_{1}^{\circ} \\
& i_{1}^{\circ} \quad\{\text { idend propertity }\}
\end{align*}
$$

This suggests the definitions and results which follow.

Definition. Given a relator F with membership relation $\epsilon_{\mathrm{F}}$, a particular class of binary relations $A \stackrel{R}{\longleftarrow} B$ is said to be F-transposable iff, for each such $R$, there exists a unique function $f: B \longrightarrow \mathrm{~F} A$ such that $\epsilon_{\mathrm{F}} \cdot f=R$ holds. This is equivalent (by skolemisation) to saying that there exists a function $\Gamma_{\mathrm{F}}$ (called the F -transpose) such that, for all such $R$ and $f$,

$$
\begin{equation*}
f=\Gamma_{\mathrm{F}} R \equiv \epsilon_{\mathrm{F}} \cdot f=R \quad \text { cf. diagram } \quad A \tag{25}
\end{equation*}
$$

In other words, such a generic F-transpose operator is the converse of membership post-composition:

$$
\begin{equation*}
\Gamma_{\mathrm{F}}=\left(\epsilon_{\mathrm{F}} \cdot\right)^{\circ} \tag{26}
\end{equation*}
$$

The two instances we have seen of (25) are the power-transpose ( $\mathrm{F} A=\mathcal{P} A$ ) and the Maybe-transpose ( $\mathrm{F} A=A+1$ ). While the former is known to be applicable to every relation [6], the latter is only applicable to simple relations, a result to be justified after we review the main properties of generic transposition. These extend those presented in [6] for the power-transpose.

Properties. Cancellation and reflection

$$
\begin{align*}
\epsilon_{\mathrm{F}} \cdot \Gamma_{\mathrm{F}} & =R  \tag{27}\\
\Gamma_{\mathrm{F}} \epsilon_{\mathrm{F}} & =i d \tag{28}
\end{align*}
$$

arise from (25) by substitutions $f:=\Gamma_{\mathrm{F}} R$ and $f:=i d$, respectively. Fusion

$$
\begin{equation*}
\Gamma_{\mathrm{F}}(T \cdot S)=\left(\Gamma_{\mathrm{F}} T\right) \cdot S \Leftarrow\left(\Gamma_{\mathrm{F}} T\right) \cdot S \text { is a function } \tag{29}
\end{equation*}
$$

arises in the same way - this time for substitution $f:=\left(\Gamma_{\mathrm{F}} T\right) \cdot S$ - as follows (assuming the side condition ensuring that $\left(\Gamma_{\mathrm{F}} T\right) \cdot S$ is a function):

$$
\begin{aligned}
\left(\Gamma_{\mathrm{F}} T\right) \cdot S=\Gamma_{\mathrm{F}} R \equiv & \epsilon_{\mathrm{F}} \cdot\left(\left(\Gamma_{\mathrm{F}} T\right) \cdot S\right)=R \\
\equiv & \{\text { associativity }\} \\
& \left(\epsilon_{\mathrm{F}} \cdot \Gamma_{\mathrm{F}} T\right) \cdot S=R \\
\equiv & \{\text { cancellation }(27)\} \\
& T \cdot S=R
\end{aligned}
$$

The side condition of (29) requires $S$ to be entire but not necessarily simple. In fact, it suffices that $\operatorname{img} S \subseteq \operatorname{ker}\left(\Gamma_{\mathrm{F}} T\right)$ since, in general, the simplicity of $f \cdot S$ equivales $\operatorname{img} S \subseteq \operatorname{ker} f:$

```
        \(\operatorname{img} S \subseteq \operatorname{ker} f\)
    \(\equiv \quad\{\) definitions \(\}\)
        \(\left(S \cdot S^{\circ}\right) \subseteq f^{\circ} \cdot f\)
    \(\equiv \quad\{i d\) is the unit of composition \(\}\)
        \(\left(S \cdot S^{\circ}\right) \subseteq f^{\circ} \cdot i d \cdot f\)
    \(\equiv \quad\{\) shunting rules (11) \(\}\)
        \(f \cdot\left(S \cdot S^{\circ}\right) \cdot f^{\circ} \subseteq i d\)
    \(\equiv \quad\{\) composition is associative ; converse of composition \(\}\)
    \((f \cdot S) \cdot(f \cdot S)^{\circ} \subseteq i d\)
    \(\equiv \quad\{\) definition of img \(\}\)
    \(\operatorname{img}(f \cdot S) \subseteq i d\)
    \(\equiv \quad\{\) simplicity \(\}\)
    \((f \cdot S)\) is simple
```

In summary, the simplicity of (entire) $S$ is a sufficient (but not necessary) condition for the fusion law (29) to hold. In particular, $S$ can be a function, and it is under this condition that the law is presented in [6] ${ }^{1}$.

Substitution $f:=\Gamma_{\mathrm{F}} S$ in (25) and cancellation (27) lead to the injectivity law,

$$
\begin{equation*}
\Gamma_{\mathrm{F}} S=\Gamma_{\mathrm{F}} R \equiv S=R \tag{30}
\end{equation*}
$$

Finally, the generic version of the absorption property,

$$
\begin{equation*}
\mathrm{F} R \cdot \Gamma_{\mathrm{F}} S=\Gamma_{\mathrm{F}}(R \cdot S) \Leftarrow R \cdot \epsilon_{\mathrm{F}} \subseteq \epsilon_{\mathrm{F}} \cdot \mathrm{~F} R \tag{31}
\end{equation*}
$$

is justified as follows:

$$
\begin{aligned}
& \quad \mathrm{F} R \cdot \Gamma_{\mathrm{F}} S=\Gamma_{\mathrm{F}}(R \cdot S) \\
& \equiv \quad\{\text { universal property }(25)\} \\
& \epsilon_{\mathrm{F}} \cdot \mathrm{~F} R \cdot \Gamma_{\mathrm{F}} S=R \cdot S \\
& \left.\equiv \quad\left\{\text { assume } \epsilon_{\mathrm{F}} \cdot \mathrm{~F} R=R \cdot \epsilon_{\mathrm{F}}\right)\right\} \\
& \quad R \cdot \epsilon_{\mathrm{F}} \cdot \Gamma_{\mathrm{F}} S=R \cdot S \\
& \equiv \quad\{\text { cancellation }(27)\} \\
& \quad R \cdot S=R \cdot S
\end{aligned}
$$

The side condition of (31) arises from the property assumed in the second step of the proof. Together with (17), it establishes the required equality by anti-symmetry, which is equivalent to writing $\mathrm{F} R=\Gamma_{\mathrm{F}}\left(R \cdot \epsilon_{\mathrm{F}}\right)$ in such situations.

[^0]Unit and inclusion. Two concepts of set-theory can be made generic in the context above. The first one has to do with singletons, that is, data structures which contain a single datum. The function $\tau_{\mathrm{F}}$ mapping every $A$ to its singleton of type F is obtainable by transposing $i d, \tau_{\mathrm{F}}=\Gamma_{\mathrm{F}} i d$, and is such that (by the fusion law) $\tau_{\mathrm{F}} \cdot f=\Gamma_{\mathrm{F}} f$. Another concept relevant in the sequel is generic inclusion, defined by

$$
\begin{equation*}
\mathrm{F} A \stackrel{\epsilon_{\mathrm{F}} \backslash \epsilon_{\mathrm{F}}}{\leftrightarrows} \mathrm{~F} A \tag{32}
\end{equation*}
$$

and involving left division (11), the relational operator which is defined by the fact that ( $R \backslash$ ) is the upper-adjoint of $(R \cdot)$ for every $R$.

## 4 Instances of Generic Transposition

In this section we discuss the power-transpose ( $\mathrm{F}=\mathcal{P}$ ) and the Maybe-transpose ( $\mathrm{F}=\mathrm{Id}+1$ ) as instances of the generic transpose (25). Unlike the former, the latter is not applicable to every relation. To conclude that only simple relations are Maybetransposable, we first show that, for every F -transposable $R$, its image is at most the image of $\epsilon_{F}$ :

$$
\begin{equation*}
\operatorname{img} R \subseteq i m g \in_{\mathrm{F}} \tag{33}
\end{equation*}
$$

The proof is easy to follow:

$$
\begin{aligned}
& \operatorname{img} R \\
&=\{\text { definition }\} \\
&= R \cdot R^{\circ} \\
&=\quad\{R \text { is F-transposable } ; \text { cancellation }(27)\} \\
&\left(\epsilon_{\mathrm{F}} \cdot \Gamma_{\mathrm{F}} R\right) \cdot\left(\epsilon_{\mathrm{F}} \cdot \Gamma_{\mathrm{F}} R\right)^{\circ} \\
&=\quad\{\text { converses }\} \\
& \epsilon_{\mathrm{F}} \cdot \Gamma_{\mathrm{F}} R \cdot\left(\Gamma_{\mathrm{F}} R\right)^{\circ} \cdot \epsilon_{\mathrm{F}}^{\circ} \\
& \subseteq \quad\left\{\Gamma_{\mathrm{F}} R \text { is simple } ; \text { monotonicity }\right\} \\
& \epsilon_{\mathrm{F}} \cdot \epsilon_{\mathrm{F}}^{\circ} \\
&=\{\text { definition }\} \\
& \operatorname{img} \quad \epsilon_{\mathrm{F}}
\end{aligned}
$$

So, $\epsilon_{\mathrm{F}}$ restricts the class of relations $R$ which are F -transposable. Concerning the power-transpose, it is easy to see that $\operatorname{img} \in_{\mathrm{F}}=\mathrm{T}$ since, for every $a, a^{\prime}$, there exists at least the set $\left\{a, a^{\prime}\right\}$ which both $a$ and $a^{\prime}$ belong to. Therefore, no restriction is imposed on img $R$ and transposition witnesses the well-known isomorphism $\left(2^{A}\right)^{B} \cong 2^{B \times A}$ (writing $2^{A}$ for $\mathcal{P} A$ and identifying every relation with its graph, a set of pairs).

By contrast, simple memberships can only be associated to the transposition of simple relations. This is what happens with $\epsilon_{\mathrm{ld}+1}=i_{1}^{\circ}$ which, as the converse of an injection, is simple (3).

Conversely, appendix A shows that all simple relations are (ld +1 )-transposable. Therefore, $(\mathrm{Id}+1)$-transposability defines the class of simple relations and witnesses isomorphism $(B+1)^{A} \cong A \rightharpoonup B$, where $A \rightharpoonup B$ denotes the set of all simple relations from $A$ to $B^{2}$.

Another difference between the two instances of generic transposition considered so far can be found in the application of the absorption property (31). That its side condition holds for the Maybe-transpose is easy to show:

$$
\begin{aligned}
& R \cdot i_{1}^{\circ} \subseteq i_{1}^{\circ} \cdot(R+i d) \\
\equiv & \quad\{\text { shunting }\} \\
& i_{1} \cdot R \subseteq(R+i d) \cdot i_{1} \\
\Leftarrow & \quad\{\text { anti-symmetry }\} \\
& i_{1} \cdot R=(R+i d) \cdot i_{1} \\
\equiv & \quad\{R+S(14) \text { is a coproduct }[6]\}
\end{aligned}
$$

Concerning the power-transpose, [6] define the absorption property for the existential image functor, $\mathrm{E} R=\Lambda(R \cdot \in)$, which coincides with the powerset relator for functions. However, E is not a relator ${ }^{3}$. So, the absorption property of the power-transpose can only be used where $R$ is a function: $\mathcal{P} f \cdot \Lambda S=\Lambda(f \cdot S)$.

Finally, inclusion (32) for the power-transpose is the set-theoretic subset ordering [6], while its Maybe instance corresponds to the expected "flat-cpo ordering":

$$
x\left(\epsilon_{\mathrm{Id}+1} \backslash \epsilon_{\mathrm{Id}+1}\right) y \equiv \forall a . x=\left(i_{1} a\right) \Rightarrow y=\left(i_{1} a\right)
$$

So Nothing will be included in anything and every "non-Nothing" $x$ will be included only in itself ${ }^{4}$.

## 5 Applications of Generic Transpose

The main purpose of representing relations by functions is to take advantage of the (sub)calculus of functions when applied to the transposed relations. In particular, transposition can be used to infer properties of relational combinators. Suppose that $f \oplus g$ is a functional combinator whose properties are known, for instance, $f \oplus g=[f, g]$ for which we know universal property

$$
k=[f, g] \equiv\left\{\begin{array}{l}
k \cdot i_{1}=f  \tag{34}\\
k \cdot i_{2}=g
\end{array}\right.
$$

[^1]We may inquire about the corresponding property of another, this time relational, combinator $R \otimes S$ induced by transposition:

$$
\begin{gather*}
\quad \Gamma_{\mathrm{F}}(R \otimes S)=\left(\Gamma_{\mathrm{F}} R\right) \oplus\left(\Gamma_{\mathrm{F}} S\right)  \tag{35}\\
\equiv \quad\{(25)\} \\
R \otimes S=\epsilon_{\mathrm{F}} \cdot\left(\left(\Gamma_{\mathrm{F}} R\right) \oplus\left(\Gamma_{\mathrm{F}} S\right)\right) \tag{36}
\end{gather*}
$$

This can happen in essentially two ways, which are described next.
Proof of universality by transposition. It may happen that the universal property of functional combinator $\oplus$ is carried intact along the move from functions to relations. A good example of this is relational coproduct, whose existence is shown in [6] to stem from functional coproducts (34) by transposition ${ }^{5}$. One only has to instantiate (34) for $k, f, g:=\Gamma_{\mathrm{F}} T, \Gamma_{\mathrm{F}} R, \Gamma_{\mathrm{F}} S$ and reason:

$$
\begin{aligned}
& \Gamma_{\mathrm{F}} T=\left[\Gamma_{\mathrm{F}} R, \Gamma_{\mathrm{F}} S\right] \equiv\left(\Gamma_{\mathrm{F}} T\right) \cdot i_{1}=\Gamma_{\mathrm{F}} R \wedge\left(\Gamma_{\mathrm{F}} T\right) \cdot i_{2}=\Gamma_{\mathrm{F}} S \\
\equiv & \quad\left\{(25) \text { and fusion }(29) \text { twice, for } S:=i_{1}, i_{2}\right\} \\
& T=\in \cdot\left[\Gamma_{\mathrm{F}} R, \Gamma_{\mathrm{F}} S\right] \equiv \Gamma_{\mathrm{F}}\left(T \cdot i_{1}\right)=\Gamma_{\mathrm{F}} R \wedge \Gamma_{\mathrm{F}}\left(T \cdot i_{2}\right)=\Gamma_{\mathrm{F}} S \\
\equiv & \{\text { injectivity }(30)\} \\
& T=\in \cdot\left[\Gamma_{\mathrm{F}} R, \Gamma_{\mathrm{F}} S\right] \equiv T \cdot i_{1}=R \wedge T \cdot i_{2}=S \\
\equiv & \left\{\text { define }[R, S]=\epsilon \cdot\left[\Gamma_{\mathrm{F}} R, \Gamma_{\mathrm{F}} S\right]\right\} \\
& T=[R, S] \equiv T \cdot i_{1}=R \wedge T \cdot i_{2}=S \\
\equiv & \quad\{\text { coproduct definition }\} \\
& {[R, S] \text { is a coproduct } }
\end{aligned}
$$

Defined in this way, relational coproducts enjoy all properties of functional coproducts, eg. fusion, absorption etc.

This calculation, however, cannot be dualized to the generalization of the splitcombinator $\langle f, g\rangle$ to relational $\langle R, S\rangle$. In fact, relational product is not a categorical product, which means that some properties will not hold, namely the fusion law,

$$
\begin{equation*}
\langle g, h\rangle \cdot f=\langle g \cdot f, h \cdot f\rangle \tag{37}
\end{equation*}
$$

when $g, h, f$ are replaced by relations. According to [6], what we have is

$$
\begin{equation*}
\langle R, S\rangle \cdot f=\langle R \cdot f, S \cdot f\rangle \tag{38}
\end{equation*}
$$

whose proof can be carried out by resorting to the explicit definition of the split combinator (15) and some properties of simple relations grounded on the so-called modular $l a w^{6}$.

[^2]In the following we present an alternative proof of (38) as an example of the calculation power of transposes combined with Reynolds abstraction theorem in the pointfree style [3]. The proof is more general and leads to other versions of the law, depending upon which transposition is adopted, that is, which class of relations is considered.

From the type of functional split,

$$
\begin{equation*}
\left\langle_{-},-\right\rangle:((A \times B) \leftarrow C) \leftarrow((A \leftarrow C) \times(B \leftarrow C)) \tag{39}
\end{equation*}
$$

we want to define the relational version of this combinator - denote it by $\left(\otimes_{-}\right)$for the time being - via the adaptation of $\langle-,-\rangle(39)$ to transposed relations, to be denoted by $\left(\__{-} \oplus\right.$ ). This will be of type

$$
\begin{equation*}
t=(\mathrm{F}(A \times B) \leftarrow C) \leftarrow((\mathrm{F} A \leftarrow C) \times(\mathrm{F} B \leftarrow C))) \tag{40}
\end{equation*}
$$

Reynolds abstraction theorem. Instead of defining (_ $\oplus_{-}$) explicitly, we will reason about its properties by applying the abstraction theorem due to J. Reynolds [19] and advertised by P. Wadler [20] under the "theorem for free" heading. We follow the pointfree styled presentation of this theorem in [3], which is remarkably elegant: let $f$ be a polymorphic function $f: t$, whose type $t$ can be written according to the following "grammar" of types:

$$
\begin{aligned}
& t::=t^{\prime} \leftarrow t^{\prime \prime} \\
& t::=\mathrm{F}\left(t_{1}, \ldots, t_{n}\right) \quad \text { for } n \text {-ary relator } \mathrm{F} \\
& t::=v \quad \text { for } v \text { a type variable (= polymorphism "dimension") }
\end{aligned}
$$

Let $V$ be the set of type variables involved in type $t ;\left\{R_{v}\right\}_{v \in V}$ be a $V$-indexed family of relations ( $f_{v}$ in case all such $R_{v}$ are functions); and $R_{t}$ be a relation defined inductively as follows:

$$
\begin{aligned}
R_{t:=\mathrm{F}\left(t_{1}, \ldots, t_{n}\right)} & =\mathrm{F}\left(R_{t_{1}}, \ldots, R_{t_{n}}\right) \\
R_{t:=v} & =R_{v} \\
R_{t:=t^{\prime} \leftarrow t^{\prime \prime}} & =R_{t^{\prime}} \leftarrow R_{t^{\prime \prime}}
\end{aligned}
$$

where $R_{t^{\prime}} \leftarrow R_{t^{\prime \prime}}$ is defined by (7). The free theorem of type $t$ reads as follows: given any function $f: t$ and $V$ as above, $f R_{t} f$ holds for any relational instantiation of type variables in $V$. Note that this theorem is a result about $t$ and holds for any polymorphic function of type $t$ independently of its actual definition ${ }^{7}$.

In the remainder of this section we deduce the free theorem of type $t$ (40) and draw conclusions about the fusion and absorption properties of relational split based on such a theorem. First we calculate $R_{t}$ :

$$
\equiv R_{t} \quad\{\text { induction on the structure of } t(40)\}
$$

[^3]\[

$$
\begin{aligned}
& \left.\left(\mathrm{F}\left(R_{A} \times R_{B}\right) \leftarrow R_{C}\right) \leftarrow\left(\left(\mathrm{F} R_{A} \leftarrow R_{C}\right) \times\left(\mathrm{F} R_{B} \leftarrow R_{C}\right)\right)\right) \\
\equiv & \quad\left\{\text { substitution } R_{A}, R_{B}, R_{C}:=R, S, Q \text { in order to remove subscripts }\right\} \\
& (\mathrm{F}(R \times S) \leftarrow Q) \leftarrow((\mathrm{F} R \leftarrow Q) \times(\mathrm{F} S \leftarrow Q)))
\end{aligned}
$$
\]

Next we calculate the free theorem of $\left(\__{-}\right): t$ :

$$
\begin{aligned}
&\left(-\oplus \_\right)\left(R_{t}\right)(-\oplus-) \\
&= \quad\left\{\text { expansion of } R_{t}\right\} \\
&\left.\left(-\oplus \_\right)(\mathrm{F}(R \times S) \leftarrow Q) \leftarrow((\mathrm{F} R \leftarrow Q) \times(\mathrm{F} S \leftarrow Q))\right)(-\oplus-) \\
&= \quad\{\text { meaning of Reynolds arrow combinator }(7)\} \\
&(-\oplus-) \cdot((\mathrm{F} R \leftarrow Q) \times(\mathrm{F} S \leftarrow Q)) \subseteq \mathrm{F}(R \times S) \leftarrow Q) \cdot(-\oplus-) \\
&= \quad\{\text { shunting }(11)\} \\
&(\mathrm{F} R \leftarrow Q) \times(\mathrm{F} S \leftarrow Q) \subseteq(-\oplus-)^{\circ} \cdot(\mathrm{F}(R \times S) \leftarrow Q) \cdot\left(-\oplus \_\right) \\
&=\quad \quad\{\text { going pointwise and }(4)\} \\
&(f, g)((\mathrm{F} R \leftarrow Q) \times(\mathrm{F} S \leftarrow Q))(h, k) \Rightarrow(f \oplus g)(\mathrm{F}(R \times S) \leftarrow Q)(h \oplus k) \\
&=\quad\{\text { product relator and }(7)\} \\
& f(\mathrm{~F} R \leftarrow Q) h \wedge g(\mathrm{~F} S \leftarrow Q) k \Rightarrow(f \oplus g) \cdot Q \subseteq \mathrm{~F}(R \times S) \cdot(h \oplus k) \\
&=\quad \quad\{\text { Reynolds arrow combinator }(7) \text { three times }\} \\
& f \cdot Q \subseteq \mathrm{~F} R \cdot h \wedge g \cdot Q \subseteq \mathrm{~F} S \cdot k \Rightarrow(f \oplus g) \cdot Q \subseteq \mathrm{~F}(R \times S) \cdot(h \oplus k)
\end{aligned}
$$

Should we replace functions $f, h, g, k$ by transposed relations $\Gamma_{\mathrm{F}} U, \Gamma_{\mathrm{F}} V, \Gamma_{\mathrm{F}} X, \Gamma_{\mathrm{F}} Z$, respectively, we obtain

$$
\begin{equation*}
\left(\left(\Gamma_{\mathrm{F}} U\right) \oplus\left(\Gamma_{\mathrm{F}} X\right)\right) \cdot Q \subseteq \mathrm{~F}(R \times S) \cdot\left(\left(\Gamma_{\mathrm{F}} V\right) \oplus\left(\Gamma_{\mathrm{F}} Z\right)\right) \tag{41}
\end{equation*}
$$

provided conjunction

$$
\begin{equation*}
\left(\Gamma_{\mathrm{F}} U\right) \cdot Q \subseteq \mathrm{~F} R \cdot\left(\Gamma_{\mathrm{F}} V\right) \wedge\left(\Gamma_{\mathrm{F}} X\right) \cdot Q \subseteq \mathrm{~F} S \cdot\left(\Gamma_{\mathrm{F}} Z\right) \tag{42}
\end{equation*}
$$

holds. Assuming (35), (41) can be re-written as

$$
\begin{equation*}
\Gamma_{\mathrm{F}}(U \otimes X) \cdot Q \subseteq \mathrm{~F}(R \times S) \cdot \Gamma_{\mathrm{F}}(V \otimes Z) \tag{43}
\end{equation*}
$$

At this point we restrict $Q$ to a function $q$ and apply the fusion law (29) without extra side conditions:

$$
\begin{equation*}
\Gamma_{\mathrm{F}}((U \otimes X) \cdot q) \subseteq \mathrm{F}(R \times S) \cdot \Gamma_{\mathrm{F}}(V \otimes Z) \tag{44}
\end{equation*}
$$

For $R, S:=i d, i d$ we will obtain -"for free" - the standard fusion law

$$
(U \otimes X) \cdot q=(U \cdot q \otimes X \cdot q)
$$

presented in [6] for the split combinator (38), ie. for $(R \otimes S)=\langle R, S\rangle$. In the reasoning, all factors involving $R$ and $S$ disappear and fusion takes place in both conjuncts of (42). Moreover, inclusion ( $\subseteq$ ) becomes equality of transposed relations - thanks to (12) - and injectivity (30) is used to remove all occurrences of $\Gamma_{\mathrm{F}}$.

Wherever $R$ and $S$ are not identities, one has different results depending on the behaviour of the chosen transposition concerning the absorption property (31).

Maybe transpose. In case of simple relations under the Maybe-transpose, absorption has no side condition, and so (44) rewrites to

$$
\begin{equation*}
(U \otimes X) \cdot q=(R \times S) \cdot(V \otimes Z) \tag{45}
\end{equation*}
$$

by further use of (12) - recall that transposed relations are functions - and injectivity (30), provided (42) holds, which boils down to $U \cdot q=R \cdot V$ and $X \cdot q=S \cdot Z$ under a similar reasoning. For $q:=i d$ and $\left(\otimes_{\_}\right)$instantiated to relational split, this becomes absorption law

$$
\begin{equation*}
\langle R \cdot V, S \cdot Z\rangle=(R \times S) \cdot\langle V, Z\rangle \quad \text { if } R, S, V, Z \text { are simple } \tag{46}
\end{equation*}
$$

In summary, our reasoning has shown that the absorption law for simple relations is a free theorem.

Power transpose. In case of arbitrary relations under the power-transpose, absorption requires $R$ and $S$ in (44) to be functions (say $r, s$ ), whereby the equation re-writes to

$$
\begin{equation*}
\Gamma_{\mathrm{F}}((U \otimes X) \cdot q) \subseteq \Gamma_{\mathrm{F}}((r \times s) \cdot(V \otimes Z)) \tag{47}
\end{equation*}
$$

provided $\Gamma_{\mathrm{F}}(U \cdot q) \subseteq \Gamma_{\mathrm{F}}(r \cdot V)$ and $\Gamma_{\mathrm{F}}(X \cdot q) \subseteq \Gamma_{\mathrm{F}}(s \cdot Z)$ hold. Again by combined use of (12) and injectivity (30) one gets

$$
\begin{equation*}
(U \otimes X) \cdot q=\mathrm{F}(r \times s) \cdot(V \otimes Z) \tag{48}
\end{equation*}
$$

provided $U \cdot q=r \cdot V$ and $X \cdot q=s \cdot Z$ hold. Again instantiating $q:=i d$ and $\left(-\otimes_{-}\right)=\langle-,\rangle_{-}$, this becomes absorption law

$$
\begin{equation*}
\langle r \cdot V, s \cdot Z\rangle=(r \times s) \cdot\langle V, Z\rangle \tag{49}
\end{equation*}
$$

Bird and Moor [6] show, in (admittedly) a rather tricky way, that product absorption holds for arbitrary relations. Our calculations have identified two restricted versions of such a law - (46) and (49) - as "free" theorems, which could be deduced in a more elegant, parametric way.

## 6 Other Transposes

So far we have considered two instances of transposition, one applicable to any relation and the other restricted to simple relations. That entire relations will have their own instance of transposition is easy to guess: it will be a variant of the power-transpose
imposing non-empty power objects (see exercise 4.45 in [6]). Dually, by (3) we will obtain a method for reasoning about surjective and injective relations.

We conclude our study of relational transposition by relating it with a data representation technique known in computer science as hashing. This will require further restricting the class of the transposable relations to coreflexive relations. On the other hand, the transpose combinator will be enriched with an extra parameter called the "hash function".

## 7 The Hash Transpose

Hashing. Hash tables are well known data structures [21, 12] whose purpose is to efficiently combine the advantages of both static and dynamic storage of data. Static structures such as arrays provide random access to data but have the disadvantage of filling too much primary storage. Dynamic, pointer-based structures (eg. search lists, search trees etc.) are more versatile with respect to storage requirements but access to data is not as immediate.

The idea of hashing is suggested by the informal meaning of the term itself: a large database file is "hashed" into as many "pieces" as possible, each of which is randomly accessed. Since each sub-database is smaller than the original, the time spent on accessing data is shortened by some order of magnitude. Random access is normally achieved by a so-called hash function, say $B{ }^{h} A$, which computes, for each data item $a$ (of type $A$ ), its location $h a$ (of type $B$ ) in the hash table. Standard terminology regards as synonyms all data competing for the same location. A set of synonyms is called a bucket.

Data collision can be handled either by eg. linear probing [21] or overflow handling [12]. The former is not a totally correct representation of a data collection. Overflow handling consists in partitioning a given data collection $S \subseteq A$ into $n$-many, disjoint buckets, each one addressed by the relevant hash index computed by $h^{8}$.

This partition can be modelled by a function $t$ of type $\mathcal{P} A{ }^{t} B$ and the socalled "hashing effect" is the following: the membership test $a \in S$ (which requires an inspection of the whole dataset $S$ ) can be replaced by $a \in t(h a)$ (which only inspects the bucket addressed by location $h a$ ). That is, equivalence

$$
\begin{equation*}
a \in S \equiv a \in t(h a) \tag{50}
\end{equation*}
$$

must hold for $t$ to be regarded as a hash table.
Hashing as a transpose. First of all, we reason about equation (50):

$$
\begin{aligned}
& a \in S \equiv a \in t(h a) \\
= & \{\text { introduce } b=h a\} \\
& a \in S \wedge b=h a \equiv a \in(t b)
\end{aligned}
$$

[^4]\[

$$
\begin{aligned}
= & \left\{\text { introduce } a=a^{\prime}\right\} \\
& a \in S \wedge a=a^{\prime} \wedge b=h a^{\prime} \equiv a \in(t b) \\
= & \quad\{\text { introduce } S \text { as a coreflexive } ; \text { converse of hash function }\} \\
= & a S a^{\prime} \wedge a^{\prime} h^{\circ} b \equiv a \in(t b) \\
= & \quad\{\text { relational composition and rule (4) }\} \\
= & a\left(S \cdot h^{\circ}\right) b \equiv a(\in \cdot t) b \\
& \quad\{\text { going pointfree }\} \\
= & \quad\{\text { power transpose }\} \\
& t=\Lambda\left(S \cdot h^{\circ}\right)
\end{aligned}
$$
\]

So, for an arbitrary coreflexive relation $A \longleftarrow^{S} A$, its hash-transpose (for a fixed hash function $B \longleftarrow^{h} A$ ) is a function $\mathcal{P} A \stackrel{t}{\longleftarrow}_{\longleftarrow^{\prime}}$, satisfying


By defining

$$
\begin{equation*}
\Theta_{h} S=\Lambda\left(S \cdot h^{\circ}\right) \tag{51}
\end{equation*}
$$

we obtain a $h$-indexed family of hash transpose operators and associated universal properties

$$
\begin{equation*}
t=\Theta_{h} S \equiv \epsilon \cdot t=S \cdot h^{\circ} \tag{52}
\end{equation*}
$$

and thus the cancellation law

$$
\begin{equation*}
\epsilon \cdot\left(\Theta_{h} S\right)=S \cdot h^{\circ} \tag{53}
\end{equation*}
$$

etc.
In summary, the hash-transpose extends the power-transpose of coreflexive relations in the sense that $\Lambda=\left(\Theta_{i d}\right)$. That is, the power-transpose is the hash-transpose using id as hash function. In practice, this is an extreme case, since some "lack of injectivity" is required of $h$ for the hash effect to take place. Note, in passing, that the other extreme case is $h=!_{A}$, where $1 \stackrel{!_{A}}{\leftrightarrows} A$ denotes the unique function of its type: there is a maximum loss of injectivity and all data become synonyms!

Hashing as a Galois connection. As powerset-valued functions, hash tables are ordered by the lifting of the subset ordering $\mathcal{P} A \leq \mathcal{P} A$ defined by $\leq=\in \backslash \in$, recall (32).

That the construction of hash tables is monotonic can be shown using the relational calculus. First we expand $\leq$ :

$$
\begin{align*}
& t \leq \\
\equiv & \{\text { pointwise ordering lifted to functions (8) }\} \\
& t \subseteq \leq \cdot t^{\prime} \\
\equiv & \{\text { definition of the subset ordering (32) }\} \\
& t \subseteq(\in \backslash \in) \cdot t^{\prime} \\
\equiv & \left\{\text { law }(R \backslash S) \cdot f=R \backslash(S \cdot f)[6], \text { since } t^{\prime} \text { is a function }\right\} \\
& t \subseteq \in \backslash\left(\epsilon \cdot t^{\prime}\right) \\
\equiv & \{(\in \cdot) \text { is lower adjoint of }(\in \backslash), \text { recall (11) }\} \\
& \in \cdot t \subseteq \in \cdot t^{\prime} \tag{54}
\end{align*}
$$

Then we reason:

$$
\begin{aligned}
& \left(\Theta_{h}\right) S \dot{( }\left(\Theta_{h}\right) R \\
\equiv & \quad\{\text { by }(54)\} \\
& \in \cdot\left(\Theta_{h}\right) S \subseteq \epsilon \cdot\left(\Theta_{h}\right) R \\
\equiv & \quad\{\text { cancellation }(53)\} \\
& S \cdot h^{\circ} \subseteq R \cdot h^{\circ} \\
\Leftarrow & \quad\left\{\left(\cdot h^{\circ}\right) \text { is monotone, cf. lower-adjoints in }(11)\right\} \\
& S \subseteq R
\end{aligned}
$$

So, the smallest hash-table is that associated with the empty relation $\perp$, that is $\Lambda \perp$, which is constant function $t=\underline{\emptyset}$, and the largest one is $t=\Lambda h^{\circ}$, the hash-transpose of $i d_{A}$. In set-theoretic terms, this is $A$ itself, the "largest" set of data of type $A$.

That the hash-transpose is not an isomorphism is intuitive: not every function $t$ mapping $B$ to $\mathcal{P} A$ will be a hash-table, because it may fail to place data in the correct bucket. Anyway, it is always possible to "filter" the wrongly placed synonyms from $t$ yielding the "largest" (correct) hash table $t^{\prime}$ it contains,

$$
t^{\prime}=t \dot{\cap} \Lambda\left(h^{\circ}\right)
$$

where, using vector notation [4], $f \dot{\cap} g$ is the lifting of $\cap$ to powerset-valued functions, $(f \dot{\cap} g) b=(f b) \cap(g b)$ for all $b$. In order to recover all data from such filtered $t^{\prime}$ we evaluate

$$
\operatorname{rng}\left(\in \cdot t^{\prime}\right)
$$

where $\mathrm{rng} R$ (read "range of $R$ ") means img $R \cap i d$. Altogether, we may define a function on powerset valued functions $\Xi_{h} t=r n g\left(\epsilon \cdot\left(t \dot{\cap} \Lambda\left(h^{\circ}\right)\right)\right)$ which extracts the coreflexive relation associated with all data correctly placed in $t$. By reconverting $\Xi_{h} t$ into a hash-table again one will get a table smaller than $t$ :

$$
\begin{equation*}
\Theta_{h}\left(\Xi_{h} t\right) \leq t \tag{55}
\end{equation*}
$$

(See proof in [18].) Another fact we can prove is a "perfect" cancellation on the other side:

$$
\begin{equation*}
\Xi_{h}\left(\Theta_{h} S\right)=S \tag{56}
\end{equation*}
$$

(See proof in [18].) These two cancellations, together with the monotonicity of the hash transpose $\Theta_{h}$ and that of $\Xi_{h}$ (this is monotone because it only involves monotonic combinators) are enough, by Theorem 5.24 in [1], to establish perfect Galois connection

$$
\Theta_{h} S \leq t \equiv S \subseteq \operatorname{rng}\left(\in \cdot\left(t \dot{\cap} \Lambda\left(h^{\circ}\right)\right)\right)
$$

cf. diagram $\left\{S\right.$ |S $\left.\subseteq i d_{A}\right\} \xrightarrow[\Xi_{h}]{\Theta_{h}}(\mathcal{P} A)^{B}$. Being a lower adjoint, the hashtranspose will distribute over union, $\Theta_{h}(R \cup S)=\left(\Theta_{h} R\right) \dot{\cup}\left(\Theta_{h} S\right)$ (so hash-table construction is compositional) and enjoy other properties known of Galois connections.

From (56) we infer that $\Theta_{h}$ (resp. $\Xi_{h}$ ) is injective (resp. surjective) and so can be regarded as a data representation (resp. abstraction) in the terminology of Fig. 1, whereby typical "database" operations such as insert, find, and remove (specified on top of the powerset algebra) can be implemented by calculation [16, 18].

## 8 Conclusions and Future Work

Functional transposition is a technique for converting relations into functions aimed at developing the algebra of binary relations indirectly via the algebra of functions. A functional transpose of a binary relation of a particular class is an "F-resultric" function where $F$ is a parametric datatype with membership. This paper attempts to develop a basis for a theory of generic transposition under the following slogan: generic transpose is the converse of membership post-composition.

Instances of generic transpose provide universal properties which all relations of particular classes of relations satisfy. Two such instances are considered in this paper, one applicable to any relation and the other applicable only to simple relations. In either cases, genericity consists of reasoning about the transposed relations without using the explicit definition of the transpose operator itself.

Our illustration of the purpose of transposition takes advantage of the free theorem of a polymorphic function. We show how to derive laws of relational combinators as free theorems involving their transposes. Finally, we relate the topic of functional
transposition with hashing as a foretaste of a generic treatment of this well-known data representation technique [18].

Concerning future work, there are several directions for improving the contents of this paper. We list some of our concerns below.

Generic membership. Our use of this device, which has received some attention in the literature $[6,10,11]$, is still superficial. We would like to organize the taxonomy of binary relations in terms of morphisms among the membership relations of their "characteristic" transposes. We would also like to assess the rôle of transposition in the context of coalgebraic process refinement [14], where structural membership and inclusion seem to play a prominent rôle.

The monadic flavour. Transposed relations are "F-resultric" functions and can so be framed in a monadic structure wherever $F$ is a monad. This is suggested in the study of the power-transpose in [6] but we haven't yet checked the genericity of the proposed constructs. This concern is related to exploiting the adjoint situations studied in [9, 8] and, in general, those involving the Kleisli category of a monad [2].

Generic hashing. Our approach to hashing in this paper stems from [16]. "Fractal" types [17] were later introduced as an attempt to generalize the process of hash table construction, based on characterizing datatype invariants by sub-objects and pullbacks. In the current paper we could dispense with such machinery by using coreflexive relations instead. The extension of this technique to other transposes based on Galois connections is currently under research [18].

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## A Proof That All Simple Relations Are Maybe-Transposable

We want to prove the existence of function $\Gamma_{\mathrm{ld}+1}$ which converts simple relations into (Id +1 )-resultric functions and is such that $\Gamma_{\mathrm{ld}+1}=\left(\epsilon_{\mathrm{ld}+1} \cdot\right)^{\circ}$, that is,

$$
\epsilon \cdot f=R \equiv f=\Gamma R
$$

omitting the Id +1 subscripts for improved readability. Our proof is inspired by [9]:

$$
\begin{aligned}
& f=\Gamma R \\
& \equiv \quad\{\text { introduce } i d\} \\
& i d \cdot f=\Gamma R \\
& \equiv \quad\{\text { coproduct reflexion }\} \\
& {\left[i_{1}, i_{2}\right] \cdot f=\Gamma R} \\
& \equiv \quad\{\text { uniqueness of } 1 \stackrel{!}{\longleftarrow} 1=i d\} \\
& {\left[i_{1}, i_{2} \cdot!\right] \cdot f=\Gamma R} \\
& \equiv \quad\{\text { require "obvious" properties }(57,58) \text { below }\} \\
& {[\Gamma i d, \Gamma \perp] \cdot f=\Gamma R} \\
& \equiv \quad\{\text { see (63) below }\} \\
& (\Gamma[i d, \perp]) \cdot f=\Gamma R \\
& \equiv \quad\{\text { the required fusion law stems from (62) below }\} \\
& (\Gamma[i d, \perp]) \cdot f=\Gamma R \\
& \equiv \quad\{\Gamma \text { is injective, see (60) below }\} \\
& {[i d, \perp] \cdot f=R} \\
& \equiv \quad\{\operatorname{recall}(24)\} \\
& \in \cdot f=R
\end{aligned}
$$

A number of facts were assumed above whose proof is on demand. Heading the list are

$$
\begin{align*}
\Gamma \perp & =i_{2} \cdot!  \tag{57}\\
\Gamma f & =i_{1} \cdot f \tag{58}
\end{align*}
$$

which match our intuition about the introduction of "error" outputs: totally undefined relation $\perp$ should be mapped to the "everywhere-Nothing" function $i_{2} \cdot$ !, while any other simple relation $R$ should "override" $i_{2} \cdot$ ! with the (non-Nothing) entries in $i_{1} \cdot R$. Clearly, entirety of $R$ will maximize the overriding - thus property (58).

Arrow $B+1 \stackrel{\Gamma R}{\rightleftarrows} A$ suggests its converse $B+1 \xrightarrow{(\Gamma R)^{\circ}} A$ expressed by

$$
\begin{equation*}
(\Gamma R)^{\circ}=\left[R^{\circ}, \cdots\right] \tag{59}
\end{equation*}
$$

which is consistent with (57) and (58) - it is easy to infer $(\Gamma \perp)^{\circ}=\left[\perp^{\circ},!^{\circ}\right]$ and $(\Gamma f)^{\circ}=\left[f^{\circ}, \perp\right]$ from (16) - and is enough to prove that $\Gamma$ has $\in=i_{1}^{\circ}$ as left-inverse,

$$
\begin{equation*}
\in \cdot \Gamma=i d \tag{60}
\end{equation*}
$$

that is, that $\Gamma$ is injective. We reason, for all $R$ :

$$
\begin{aligned}
& i_{1}^{\circ} \cdot \Gamma R=R \\
\equiv & \{\text { take converses }\} \\
& (\Gamma R)^{\circ} \cdot i_{1}=R^{\circ} \\
\equiv & \{\text { assumption }(59)\} \\
& {\left[R^{\circ}, \cdots\right] \cdot i_{1}=R^{\circ} } \\
\equiv & \{\text { coproduct cancellation }\} \\
& R^{\circ}=R^{\circ}
\end{aligned}
$$

The remaining assumptions in the proof require us to complete the construction of the transpose operator. Inspired by (57) and (58), we define

$$
\begin{equation*}
\Gamma_{\mathrm{ld}+1} R \stackrel{\text { def }}{=}\left(i_{2} \cdot!\right) \dagger\left(i_{1} \cdot R\right) \tag{61}
\end{equation*}
$$

where $R \dagger S$, the "relation override" operator", is defined by $(R \cdot(i d-\operatorname{ker} S)) \cup S$, or simply by $R \dagger S=S \triangleleft S \triangleright R$ if we resort to relational conditionals [1]. This version of the override operator is useful in proving the particular instance of fusion (29) required in the proof: this stems from

$$
\begin{equation*}
(R \dagger S) \cdot f=(R \cdot f) \dagger(S \cdot f) \tag{62}
\end{equation*}
$$

itself a consequence of a fusion property of the relational conditional [1].
It can be checked that (61) validates all other previous assumptions, namely $(57,58)$ and (59). Because $R \dagger S$ preserves entirety on any argument and simplicity on both (simultaneously), $\Gamma R$ will be a function provided $R$ is simple.

The remaining assumption in the proof stems from equalities

$$
\begin{equation*}
[\Gamma i d, \Gamma \perp]=\Gamma[i d, \perp]=\Gamma\left(i_{1}^{\circ}\right)=\operatorname{img} i_{1} \cup \operatorname{img} i_{2}=i d \tag{63}
\end{equation*}
$$

which arise from (61) and the fact that $i_{1}$ and $i_{2}$ are (dis)jointly surjective injections.

[^5]
[^0]:    ${ }^{1}$ Cf. exercise 5.9 in [6]. See also exercise 4.48 for a result which is of help in further reasoning about the side condition of (29).

[^1]:    ${ }^{2}$ This isomorphism is central to the data refinement calculus presented in [15].
    ${ }^{3}$ See [10] and exercise 5.15 in [6].
    ${ }^{4}$ This is, in fact, the ordering <= which is derived for Maybe as instance of the Ord class in the Haskell Prelude [13].

[^2]:    ${ }^{5}$ For the same outcome without resorting to transposition see §2.5.2 of [10].
    ${ }^{6}$ See Exercise 5.9 in [6].

[^3]:    ${ }^{7}$ See [3] for comprehensive evidence on the the power of this theorem when combined with Galois connections, which stems basically from the interplay between equations (5) and (6).

[^4]:    ${ }^{8}$ In fact, such buckets ("collision segments") are but the equivalence classes of ker $h$ restricted to $S$ (note that the kernel of a function is always an equivalence relation).

[^5]:    ${ }^{9}$ This extends the map override operator of VDM [7].

