# Matrices are Arrows! an AOP perspective on (typed) linear algebra 

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## Context and Motivation

- The advent of on-chip parallelism poses many challenges to current programming languages.
- Traditional approaches based on compiler + hand-coded optimization are giving place to trendy generative techniques, based on DSLs for high-level program transformation.
- In areas such as scientific computing, image/video processing, the bulk of the work performed by so-called kernel functions.
- Examples of kernels are matrix-matrix multiplication (MMM), the discrete Fourier transform (DFT), etc.
- Kernel optimization has become extraordinarily difficult due to the complexity of current computing platforms.


## Teaching computers to write fast numerical code

In the SPIRAL Group (CMU), a DSL has been defined (OL) [1] to specify kernels in a data-independent way.

- OL is derived from mathematics (thus declarative) and describes the structure of a computation in an implementation-independent form. Divide-and-conquer algorithms are described as $\mathbf{O L}$ breakdown rules.
- By recursively applying these rules a space of algorithms for a desired kernel can be generated.
Rationale behind SPIRAL:
- Target imperative code is too late for numeric processing kernel optimization.
- Such optimization can be elegantly and efficiently performed well above in the design chain once the maths themselves are expressed in an index-free style.


## Synergy

- Parallel between the pointfree notation of OL and relational algebra is obvious.
- Rich calculus of algebraic rules.
- Relational calculus is typed once relations are regarded as arrows in the Rel allegory.
- What about the matrix calculus?


## Sample of OL (Operator language) [1]

| name | definition |
| :--- | :--- |
| Linear, arity (1,1) |  |
| $\quad$ identity | $I_{n}: \mathbb{C}^{n} \rightarrow \mathbb{C}^{n} ; \mathbf{x} \mapsto \mathbf{x}$ |
| vector flip | $J_{n}: \mathbb{C}^{n} \rightarrow \mathbb{C}^{n} ;\left(x_{i}\right) \mapsto\left(x_{n-i}\right)$ |
| transposition of an $m \times n$ matrix | $L_{m}^{m n}: \mathbb{C}^{m n} \rightarrow \mathbb{C}^{m n} ; \mathbf{A} \mapsto \mathbf{A}^{T}$ |
| matrix $M \in \mathbb{C}^{m \times n}$ | $\mathrm{M}: \mathbb{C}^{n} \rightarrow \mathbb{C}^{m} ; \mathbf{x} \mapsto M \mathbf{x}$ |
| Multilinear, arity (2,1) |  |
| $\quad$ Point-wise product | $\mathrm{P}_{n}: \mathbb{C}^{n} \times \mathbb{C}^{n} \rightarrow \mathbb{C}^{n} ;\left(\left(x_{i}\right),\left(y_{i}\right)\right) \mapsto\left(x_{i} y_{i}\right)$ |
| Scalar product | $\mathrm{S}_{n}: \mathbb{C}^{n} \times \mathbb{C}^{n} \rightarrow \mathbb{C} ;\left(\left(x_{i}\right),\left(y_{i}\right)\right) \mapsto \Sigma\left(x_{i} y_{i}\right)$ |
| Kronecker product | $\left.\mathrm{K}_{m \times n}: \mathbb{C}^{m} \times \mathbb{C}^{n} \rightarrow \mathbb{C}^{m n} ;\left(\left(x_{i}\right), \mathbf{y}\right)\right) \mapsto\left(x_{i} \mathbf{y}\right)$ |
| Others |  |
| Fork | $\operatorname{Fork}_{n}: \mathbb{C}^{n} \rightarrow \mathbb{C}^{n} \times \mathbb{C}^{n} ; \mathbf{x} \mapsto(\mathbf{x}, \mathbf{x})$ |
| Split | $\operatorname{Split}_{n}: \mathbb{C}^{n} \rightarrow \mathbb{C}^{n / 2} \times \mathbb{C}^{n / 2} ; \mathbf{x} \mapsto\left(\mathbf{x}, \mathbf{x}^{L}\right)$ |
| Concatenate | $\oplus \mathbb{C}_{n}: \mathbb{C}^{n} \times \mathbb{C}^{m} \rightarrow \mathbb{C}^{n+m} ;(\mathbf{x}, \mathbf{y}) \mapsto \mathbf{x} \oplus \mathbf{y}$ |
| Duplication | $\operatorname{dup}_{n}^{m}: \mathbb{C}^{n} \rightarrow \mathbb{C}^{n m} ;\left(\mathbf{x} \mapsto \mathbf{x} \otimes I_{m}\right.$ |
| Min | $\min _{n}: \mathbb{C}^{n} \times \mathbb{C}^{n} \rightarrow \mathbb{C}^{n} ;(\mathbf{x}, \mathbf{y}) \mapsto\left(\min \left(x_{i}, y_{i}\right)\right)$ |
| Max | $\max _{n}: \mathbb{C}^{n} \times \mathbb{C}^{n} \rightarrow \mathbb{C}^{n} ;(\mathbf{x}, \mathbf{y}) \mapsto\left(\max \left(x_{i}, y_{i}\right)\right)$ |

Table 1. Definition of basic operators. The operators are assumed to operate on complex numbers but other base sets are possible. Boldface fonts represent vectors or matrices linearized in memory. Superscripts $U$ and $L$ represent the upper and lower half of a vector. A vector is sometimes written as $\mathbf{x}=\left(x_{i}\right)$ to identify the components.

## Comments

We believe a number of improvements can be performed concerning

- the OL notation itself
- the layout of its calculus
- Its effectiveness for calculation/transformation purposes

By the way:

- Looking at linear algebra textbooks we see a diversity of approaches, ways of defining/describing kernel algorithms.
- Textbooks often explain matrix operations by resorting to for-loop notation.
- How "algebraic" is this?


## MMM as inspiration about what to do

From the Wikipedia:


Index-wise definition

$$
C_{i j}=\sum_{k=1}^{2} A_{i k} \times B_{k j}
$$

## MMM as inspiration about what to do

From the Wikipedia:


Index-wise definition

$$
C_{i j}=\sum_{k=1}^{2} A_{i k} \times B_{k j}
$$

Hiding indices $i, j, k$ :


Index-free

$$
C=A \cdot B
$$

## Matrices are Arrows

Given

$$
\begin{aligned}
& A=\left[\begin{array}{ccc}
a_{11} & \cdots & a_{1 n} \\
\vdots & \ddots & \vdots \\
a_{m 1} & \cdots & a_{m n}
\end{array}\right]_{m \times n} \\
& B=\left[\begin{array}{ccc}
b_{11} & \cdots & b_{1 k} \\
\vdots & \ddots & \vdots \\
b_{u 1} & \cdots & b_{n k}
\end{array}\right]_{n \times k}
\end{aligned}
$$

$$
m<A
$$

$$
n \lessdot \frac{B}{\longleftarrow} k
$$

## Matrices are Arrows

Given

$$
\begin{array}{ll}
A & =\left[\begin{array}{ccc}
a_{11} & \cdots & a_{1 n} \\
\vdots & \ddots & \vdots \\
a_{m 1} & \cdots & a_{m n}
\end{array}\right]_{m \times n} \\
B=\left[\begin{array}{ccc}
b_{11} & \ldots & b_{1 k} \\
\vdots & \ddots & \vdots \\
b_{u 1} & \ldots & b_{n k}
\end{array}\right]_{n \times k} & n<{ }^{A}
\end{array}
$$

Define


## Category of matrices

As guessed above:

- Under MMM $(A \cdot B)$, matrices form a category whose objects are matrix dimensions and whose morphisms $m<^{A} n, n<^{B} k$ are the matrices themselves.
- Every identity $n<^{i d} n$ is the diagonal of size $n$, that is, $i d(r, c) \triangleq r=c$ under the $(0,1)$ encoding of the Booleans:

$$
i d_{n}=\left[\begin{array}{cccc}
1 & 0 & \cdots & 0 \\
0 & 1 & \cdots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
0 & 0 & \cdots & 1
\end{array}\right]_{n \times n} \quad n \ll{ }^{i d_{n}} n
$$

## Category of matrices

Looking closer:

- Such a category is Abelian - every homset forms an aditive Abelian group ( $\mathbf{A b}$-category) such that composition is bilinear relative to + :

$$
\begin{align*}
M \cdot(N+L) & =M \cdot N+M \cdot L  \tag{1}\\
(N+L) \cdot K & =N \cdot K+L \cdot K \tag{2}
\end{align*}
$$

- It has biproducts, where a biproduct diagram

$$
\begin{equation*}
a \stackrel{i_{1}}{\stackrel{\pi_{1}}{\leftrightarrows}} c \underset{i_{2}}{\stackrel{\pi_{2}}{\longleftrightarrow}} b \tag{3}
\end{equation*}
$$

is such that

$$
\begin{align*}
\pi_{1} \cdot i_{1} & =i d_{a}  \tag{4}\\
\pi_{2} \cdot i_{2} & =i d_{b}  \tag{5}\\
i_{1} \cdot \pi_{1}+i_{2} \cdot \pi_{2} & =i d_{c} \tag{6}
\end{align*}
$$

## Biproduct $=$ product + coproduct

Theorem:
" Two objects $a$ and $b$ in Ab-category $A$ have a product in $A$ iff they have a biproduct in $A$. Specifically, given a biproduct diagram, the object $c$ with the projections $\pi_{1}$ and $\pi_{2}$ is a product of $a$ and $b$, while, dually, $c$ with $i_{1}$ and $i_{2}$ is a coproduct." (MacLane [2], pg. 194)


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"Deja vu"?
Yes, in relation algebra, for $\pi_{1}=i_{1}^{\circ}$ and $\pi_{2}=i_{2}^{\circ}$ :

$$
[R, S]=\left(R \cdot i_{1}^{\circ}\right) \cup\left(S \cdot i_{2}^{\circ}\right) \quad \text { cf. } \quad A \xrightarrow[i_{1}]{\longrightarrow} A+B<i_{2}^{i_{2}} B
$$

## Deja vu

In fact, within relations

$$
\begin{aligned}
& i_{1}^{\circ} \cdot i_{1}=i d \\
& i_{2}^{\circ} \cdot i_{2}=i d
\end{aligned}
$$

meaning that $i_{k=1,2}$ are injections (kernels both reflexive and coreflexive) and

$$
i_{1} \cdot i_{1}^{\circ} \cup i_{2} \cdot i_{2}^{\circ}=i d
$$

meaning that they are jointly surjective (images together are reflexive and coreflexive).
In linear algebra, however, biproducts are far many and more interesting! Let us see why.

## The Puzzle

The biproduct definition is declarative, in order to build upon this concept, we need to re-interpret its axioms constructively. To do so is to solve the following equation system:

$$
\begin{cases}\pi_{1} \cdot i_{1} & =i d_{a} \\ \pi_{2} \cdot i_{2} & =i d_{b} \\ i_{1} \cdot \pi_{1}+i_{2} \cdot \pi_{2} & =i d_{c}\end{cases}
$$

"In other words, the equations [above] contain the familiar calculus of matrices." Mac Lane

## The "standard" biproduct

In this biproduct, coproduct is column-wise join $[A \mid B]$ and product is row-wise join $\left\langle\frac{A}{B}\right\rangle$. As in relation algebra, $\pi_{1}=i_{1}^{\circ}$ and $\pi_{2}=i_{2}^{\circ}$, where $M^{\circ}$ is the transpose of $M$, and:

$$
\begin{align*}
{[A \mid B] } & =A \cdot \pi_{1}+B \cdot \pi_{2}  \tag{7}\\
\left\langle\frac{A}{B}\right\rangle & =\left[A^{\circ} \mid B^{\circ}\right]^{\circ} \tag{8}
\end{align*}
$$

Thus

$$
\begin{equation*}
\left\langle\frac{A}{B}\right\rangle=i_{1} \cdot A+i_{2} \cdot B \tag{9}
\end{equation*}
$$

## Diagram



## Universal properties

Product:

$$
X=\left\langle\frac{A}{B}\right\rangle \equiv\left\{\begin{array}{c}
\pi_{1} \cdot X=A  \tag{10}\\
\pi_{2} \cdot X=B
\end{array}\right.
$$

Coproduct:

$$
X=[A \mid B] \equiv\left\{\begin{array}{l}
X \cdot i_{1}=A  \tag{11}\\
X \cdot i_{2}=B
\end{array}\right.
$$

Both:

$$
X=\left(\begin{array}{l|l}
A & C  \tag{12}\\
\hline B & D
\end{array}\right) \equiv\left\{\begin{array}{l}
\pi_{1} \cdot X \cdot i_{1}=A \\
\pi_{1} \cdot X \cdot i_{2}=C \\
\pi_{2} \cdot X \cdot i_{1}=B \\
\pi_{2} \cdot X \cdot i_{2}=D
\end{array}\right.
$$

## Elementary matrix AOP

Reflection

$$
\begin{align*}
\left\langle\frac{\pi_{1}}{\pi_{2}}\right\rangle & =i d  \tag{13}\\
{\left[i_{1} \mid i_{2}\right] } & =i d \tag{14}
\end{align*}
$$

Fusion

$$
\begin{align*}
\left\langle\frac{A}{B}\right\rangle \cdot C & =\left\langle\frac{A \cdot C}{B \cdot C}\right\rangle  \tag{15}\\
C \cdot[A \mid B] & =[C \cdot A \mid C \cdot B] \tag{16}
\end{align*}
$$

## Abide laws

Not only the exchange law

$$
\left.\left\langle\frac{\left.\left[\begin{array}{c|c}
A & B
\end{array}\right]=\left[\left.\left\langle\frac{A}{C}\right\rangle \right\rvert\,\left\langle\frac{B}{D}\right\rangle\right]=\left(\begin{array}{c|c}
A & B  \tag{17}\\
\hline C & D
\end{array}\right]\right) . D}{[C}\right| \begin{array}{c}
D
\end{array}\right)
$$

but also

$$
\begin{align*}
\left\langle\frac{A}{B}\right\rangle+\left\langle\frac{C}{D}\right\rangle & =\left\langle\frac{A+C}{B+D}\right\rangle  \tag{18}\\
{[A \mid B]+[C \mid D] } & =[A+C \mid B+D] \tag{19}
\end{align*}
$$

Parentheses [ | ] and $\left\langle \_\right\rangle$will be saved wherever unnecessary.

## Putting things to work

Elementary divide and conquer matrix multiplication:

$$
\begin{equation*}
[R \mid S] \cdot\left\langle\frac{U}{V}\right\rangle=R \cdot U+S \cdot V \tag{20}
\end{equation*}
$$

Calculation:

$$
\begin{aligned}
& {[R \mid S] \cdot\left\langle\frac{U}{V}\right\rangle } \\
= & \{(9)\} \\
= & {[R \mid S] \cdot\left(i_{1} \cdot U+i_{2} \cdot V\right) } \\
= & \{\text { bilinearity (1) }\} \\
= & {[R \mid S] \cdot i_{1} \cdot U+[R \mid S] \cdot i_{2} \cdot V } \\
& \{+ \text {-cancellation }\}
\end{aligned}
$$

## Putting things to work

Blockwise MMM:

$$
\left(\begin{array}{l|l}
R & S  \tag{21}\\
\hline U & V
\end{array}\right) \cdot\left(\begin{array}{c|c}
A & B \\
\hline C & D
\end{array}\right)=\left(\begin{array}{c|c}
R A+S C & R B+S D \\
\hline U A+V C & U B+V D
\end{array}\right)
$$

Calculation:

$$
=\begin{gathered}
\left.\left[\left.\left\langle\frac{R}{U}\right\rangle \right\rvert\,\left\langle\frac{S}{V}\right\rangle\right] \cdot\left\langle\frac{[A \mid B]}{[C \mid D}\right]\right\rangle \\
\quad\{\text { divide and conquer (20) \}} \\
\frac{R}{U} \cdot[A \mid B]+\frac{S}{V} \cdot[C \mid D]
\end{gathered}
$$

## Putting things to work

$$
\begin{aligned}
& =\quad\{\text { fusion }-\times \text { \} } \\
& \left\langle\begin{array}{l|l|l}
R \cdot\left[\begin{array}{l|l}
A & B \\
\hline U \cdot[A & B
\end{array}\right]
\end{array}\right\rangle+\left\langle\begin{array}{llll}
S \cdot\left[\begin{array}{l|l}
C & D
\end{array}\right] \\
\hline V \cdot\left[\begin{array}{l|l}
C & D
\end{array}\right]
\end{array}\right. \\
& =\quad\{\text { fusion- }+ \text { \} } \\
& \left.\left.\left\langle\begin{array}{c|c}
{[R \cdot A} & R \cdot B
\end{array}\right]\right\rangle+\left\langle\begin{array}{l|l|l}
{[S \cdot C} & S \cdot D] \\
\hline U \cdot A & U \cdot B
\end{array}\right]\right\rangle \\
& =\{\text { abide } \times \text { \} } \\
& \left\langle\begin{array}{c}
{[R \cdot A \mid R \cdot B]+[S \cdot C \mid S \cdot D]} \\
\hline[U \cdot A \mid U \cdot B]+[V \cdot C \mid V \cdot D]
\end{array}\right\rangle \\
& =\quad\{\text { abide- }+ \text { \} }
\end{aligned}
$$

## Putting things to work

$$
\begin{aligned}
& \left\langle\begin{array}{c|c}
{[R \cdot A+S \cdot C} & R \cdot B+S \cdot D] \\
\hline U \cdot A+V \cdot C & U \cdot B+V \cdot D]
\end{array}\right\rangle \\
& =\{\text { exchange law (17) }\} \\
& \left(\begin{array}{c|c}
R A+S C & R B+S D \\
\hline U A+V C & U B+V D
\end{array}\right)
\end{aligned}
$$

## (Categorial) sum $=$ product

Definitions:

$$
\begin{align*}
A \oplus B & =\left[i_{1} \cdot A \mid i_{2} \cdot B\right]  \tag{22}\\
A \odot B & =\left\langle\frac{A \cdot \pi_{1}}{B \cdot \pi_{2}}\right\rangle \tag{23}
\end{align*}
$$

Fact:

$$
\begin{equation*}
A \oplus B=A \odot B \tag{24}
\end{equation*}
$$

Calculation:

$$
\begin{aligned}
A \oplus B & =\left[i_{1} \cdot A \mid i_{2} \cdot B\right] \\
& =\left(\begin{array}{c|c}
A & 0 \\
\hline 0 & B
\end{array}\right) \\
& =i_{1} \cdot A \cdot \pi_{1}+i_{2} \cdot B \cdot \pi_{2} \\
& =\left\langle\frac{A \cdot \pi_{1}}{B \cdot \pi_{2}}\right\rangle \\
& =A \odot B
\end{aligned}
$$

## (Bi)functors

That $A \oplus B(=A \odot B)$ is a (bi)functor is immediate from the universal properties. A number of standard properties arise:

$$
\begin{align*}
i d \oplus i d & =i d  \tag{25}\\
(A \oplus B) \cdot(C \oplus D) & =(A \cdot C \oplus B \cdot D)  \tag{26}\\
{[A \mid B] \cdot(C \oplus D) } & =[A \cdot C \mid B \cdot D]  \tag{27}\\
(A \odot B) \cdot \frac{C}{D} & =\frac{A \cdot C}{B \cdot D} \tag{28}
\end{align*}
$$

## Polymorphic matrices

Matrices $i_{1}, i_{2}, \pi_{1}, \pi_{2}$ are polymorphic, as exhibited by "free theorems":

$$
\begin{align*}
A \cdot i_{1} & =i_{1} \cdot(A \oplus B)  \tag{29}\\
A \cdot \pi_{1} & =\pi_{1} \cdot(A \odot B) \tag{30}
\end{align*}
$$

and so on. But there are more examples of matrix polymorphism: id itself is polymorphic, cf. "free theorem":

$$
\begin{equation*}
A \cdot i d=i d \cdot A=A \tag{31}
\end{equation*}
$$

## Polymorphic matrices

Matrix id is a special case of a diagonal matrix: given scalar a, we define

$$
a_{n}=\left[\begin{array}{cccc}
a & 0 & \cdots & 0 \\
0 & a & \cdots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
0 & 0 & \cdots & a
\end{array}\right]_{n \times n} \quad n \longleftarrow a_{n} n
$$

Clearly, id $=1$. Also note that a can be defined blockwise, since $a=a \oplus a$, for $n>1$ and arbitrary choice of block sizes.

## Polymorphic matrices

(Pointfree) scalar product: define

$$
\begin{equation*}
a A=a \cdot A \tag{32}
\end{equation*}
$$

"Free theorem":

$$
\begin{equation*}
A \cdot a=a \cdot A \quad(=a A) \tag{33}
\end{equation*}
$$

## Flipping

$$
\begin{equation*}
\text { flip } X=\text { swap } \cdot X \tag{34}
\end{equation*}
$$

where

$$
\begin{aligned}
& \operatorname{swap} 1=1 \\
& \operatorname{swap}(n+m)=\left(\begin{array}{c|c}
0 & \text { swap } m \\
\hline \operatorname{swap} n & 0
\end{array}\right)
\end{aligned}
$$

Fact:

$$
\begin{equation*}
\operatorname{swap}(n+m) \cdot \operatorname{swap}(m+n)=i d \tag{35}
\end{equation*}
$$

Thus:

$$
\text { flip }(\text { flip } X)=X
$$

## Gaussian elimination

Motivation:

$$
\operatorname{ge}\left(\begin{array}{c|c}
x & y \\
\hline z & k
\end{array}\right)=\left(\begin{array}{c|c}
x & y \\
\hline z-\frac{1}{x} z x & k-\frac{1}{x} z y
\end{array}\right)
$$

Generalization:

$$
\operatorname{ge}\left(\begin{array}{c|c}
x & M \\
\hline N & Q
\end{array}\right)=\left[\begin{array}{c|c}
x & M \\
\hline 0 & \operatorname{ge}\left(Q-\frac{N}{x} \cdot M\right)
\end{array}\right]
$$

Types:


## Another solution

Step of gaussian elimination?

$$
\left.\begin{array}{l}
\pi_{1}^{\prime} \cdot\left[\begin{array}{ll}
a_{11} & a_{12} \\
a_{21} & a_{22}
\end{array}\right]=\left[\begin{array}{ll}
a_{11} & a_{12}
\end{array}\right] \\
\pi_{2}^{\prime} \cdot\left[\begin{array}{ll}
a_{11} & a_{12} \\
a_{21} & a_{22}
\end{array}\right]=\left[\alpha a_{11}+a_{21} \quad \alpha a_{12}+a_{22}\right.
\end{array}\right]
$$

Building Elementary Matrices?

$$
\left.\left\langle\frac{\pi_{1}^{\prime}}{\pi_{2}^{\prime}}\right\rangle=\left\langle\frac{[1}{} \frac{0}{1}\right]\left[\begin{array}{ll}
\alpha & 1
\end{array}\right]\right\rangle=\left[\begin{array}{ll}
1 & 0 \\
\alpha & 1
\end{array}\right]
$$

## Tensor/Kroneker product

$$
\left[\begin{array}{ll}
a_{11} & a_{12} \\
a_{21} & a_{22}
\end{array}\right] \otimes\left[\begin{array}{ll}
b_{11} & b_{12} \\
b_{21} & b_{22}
\end{array}\right]=\left[\begin{array}{llll}
a_{11} b_{11} & a_{11} b_{12} & a_{12} b_{11} & a_{12} b_{12} \\
a_{11} b_{21} & a_{11} b_{22} & a_{12} b_{21} & a_{12} b_{22} \\
a_{21} b_{11} & a_{21} b_{12} & a_{22} b_{11} & a_{22} b_{12} \\
a_{21} b_{21} & a_{21} b_{22} & a_{22} b_{21} & a_{22} b_{22}
\end{array}\right]
$$

$$
\begin{aligned}
& x \otimes A=x A \\
& \frac{C}{D} \otimes A=\frac{C \otimes A}{D \otimes A} \\
& {[C \mid D] \otimes A=C \otimes A \mid D \otimes A}
\end{aligned}
$$

## Striding

Kronecker notation:

$$
A=\left[\begin{array}{ll}
a_{11} & a_{12} \\
a_{21} & a_{22} \\
a_{31} & a_{32}
\end{array}\right]
$$

$$
\bar{A}=\left[\begin{array}{l}
a_{11} \\
a_{21} \\
a_{31} \\
a_{12} \\
a_{22} \\
a_{32}
\end{array}\right]
$$

A kind of exponential?
Universal Law

$$
K=\bar{A} \equiv A=a p \cdot(K \otimes i d)
$$

## Indeed

J. Magnus book (1999)

$$
\begin{aligned}
\text { vec } a b^{T} & =b \otimes a \\
\operatorname{vec} A & =\left(A^{T} \otimes I_{m}\right) \times \operatorname{vec} I_{m} \\
\boldsymbol{v e c} A & =\left(I_{n} \otimes A\right) \times \operatorname{vec} I_{n}
\end{aligned}
$$

## Comments?

Why Abstract Nonsense
"A category can be seen as a structure that formalizes a mathematician's description of a type of structure"

Barr's et al

Could We Pay Back Mathematics?

圊 Franz Franchetti, Frédéric de Mesmay, Daniel McFarlin, and Markus Püschel.
Operator language: A program generation framework for fast kernels.
In IFIP Working Conference on Domain Specific Languages (DSL WC), 2009.

围 S. MacLane.
Categories for the Working Mathematician.
Springer-Verlag, New-York, 1971.

