Algebraic and Coalgebraic Methods in Software Development

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1st Module: Basic category theory for the software sciences



Software is pre-science — formal but not fully calculational

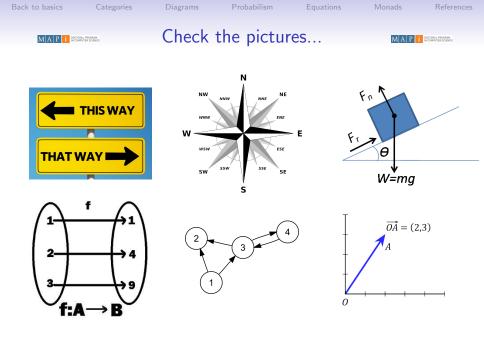
Software is too diverse - many approaches, lack of unity

Software is too wide a concept — from assembly to quantum programming

Can you think of a **unified** theory able to express and reason about software *in general*?

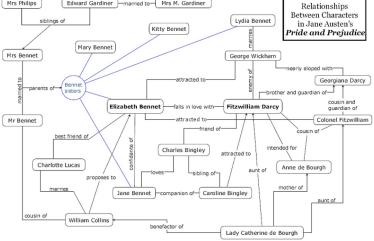
Put in another way:

Is there a "lingua franca" for the software sciences?



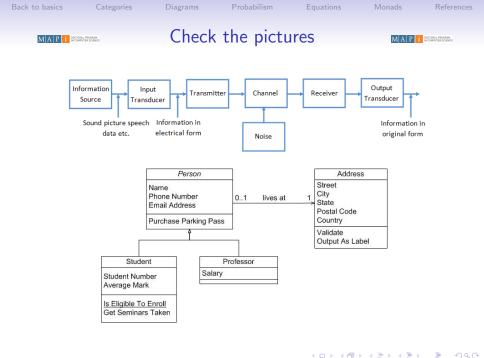
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(Wikipedia: **Pride and Prejudice**, by Jane Austin, 1813.)

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Which **graphical** device have you found **common** to **all** pictures?

Your answer is likely to match what comes next...





Arrows! Thus we identify a (graphical) ingredient **common** to describing (several) **different** fields of human activity.

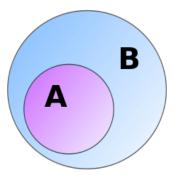
For this ingredient to be able to support a **generic** theory of systems, mind the remarks:

- We need a **generic** notation able to cope with very distinct problem domains, e.g. **process** theory versus **database** theory, for instance.
- Notation is not enough we need to **reason** and **calculate** about software.

- Semantics-rich **diagram** representations are welcome.
- System description may have a **quantitative** side too.

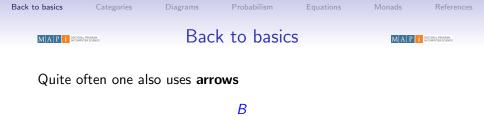


Recall your basic school maths. In set theory, for instance,



you wrote $A \subseteq B$ meaning to say that A is a subset of B.

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to say the same thing, $A \subseteq B$.

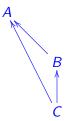
Graphical notations (Venn diagrams, arrow notation) are useful.

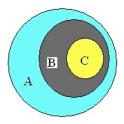
Take, for instance,

 $\begin{array}{l} A \subseteq A \text{ holds (reflexivity)} \\ C \subseteq B \text{ and } B \subseteq A \text{ then } C \subseteq A \text{ holds (transitivity)} \\ A \subseteq B \text{ and } B \subseteq A \text{ then } B = A \text{ (anti-symmetry)} \end{array}$



Diagram for the **transitive** property:





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Diagrams for the other two properties:

A = B



Divisibility — write $n \sqsubseteq m$ to say that n divides m (in \mathbb{N}).

Natural number divisibility basic facts:

 $n \sqsubseteq n$ holds (reflexivity) $n \sqsubseteq m$ and $m \sqsubseteq k$ then $n \sqsubseteq k$ holds (transitivity) $n \sqsubseteq m$ and $m \sqsubseteq n$ then m = n (anti-symmetry)

Again we may use **arrows** and **diagrams** to say the same thing, e.g.



to mean the middle property (and so on).



Statement $2 \sqsubseteq 6$ is valid but but it provides **no evidence** about **why** such a relationship holds.

We argue:

- $3 \cdot 2 = 6$;
- that is, $\exists k = 3$ such that $k \cdot 2 = 6$;
- that is, 6 is a **multiple** of 2.

In general,

 $n \sqsubseteq m$ iff $\exists k$ st $m = k \cdot n$

Why so much ado for so *little*? How about drawing

$$m \atop k \atop n$$

to mean the same? Take k as the witness — evidence, proof — of the divisibility relationship.



This helps in providing evidence of the properties themselves by calculating **new** witnesses from **given** witnesses.

Such is the case of transitivity



and reflexivity:

 $n \\ 1 \\ n$

Moreover:

 $n \\ \uparrow n \\ 1$

since 1 divides any number (etc).

A graphical, **constructive** way of stating divisibility properties.



Thus two well-known properties of multiplication, **associativity**

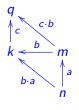
$$c \cdot (b \cdot a) = (c \cdot b) \cdot a$$
 (1)

and identity

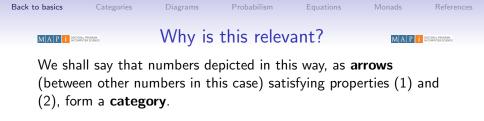
 $1 \cdot \mathbf{a} = \mathbf{a} \cdot 1 = \mathbf{a} \tag{2}$

are depicted aside in diagrammatic form.

Note how the arrows type numbers with other numbers.







Again, "much ado for nothing"? Wait and see — the concept of a **category** will prove very powerful and generic.

Another way to put it, more computer science oriented:

Arrow $m \stackrel{k}{\leftarrow} n$ means that number k has become **typed** by an **input** type n and an **output** type m (all natural numbers).

Types play a **major** role in scientific software engineering, as we shall see.



This example of a category is "boring" — there are natural numbers everywhere, both labelling the arrows and their endpoints.

Is there any other construction in mathematics or computer science which we could describe by arrows

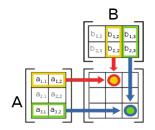
 $m \stackrel{k}{\leftarrow} n$

where n, m are still natural numbers, but k is not one such number?

Yes — the Wikipedia describes one (click <u>this</u> link) as shown in the next slide.



Recall matrix multiplication:

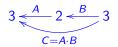


Index-wise definition

$$C_{ij} = \sum_{k=1}^{2} A_{ik} imes B_{kj}$$

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The same in arrow notation



Index-free notation

$$C = A \cdot B$$



Given

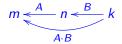
$$A = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix}_{m \times n}$$
$$B = \begin{bmatrix} b_{11} & \dots & b_{1k} \\ \vdots & \ddots & \vdots \\ b_{n1} & \dots & b_{nk} \end{bmatrix}_{n \times k}$$
efine

$$m \stackrel{A}{\leftarrow} n$$

 $n \stackrel{B}{\leftarrow} k$

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as matrix A multiplied by matrix B.



As is well-known, matrix multiplication is **associative**,

 $C \cdot (B \cdot A) = (C \cdot B) \cdot A$ (3)

with identity

 $id \cdot A = A \cdot id = A$ (4)

Each identity matrix $n \stackrel{id}{\longleftarrow} n$ is the **diagonal** of size *n*, that is, $id_{j,i} \triangleq j = i$ under the (0, 1) encoding of the Booleans (aside).





Summary:

- Matrices form a category whose objects are matrix dimensions and whose arrows m < A n, n < B k are the matrices themselves.
- **Composition** $A \cdot B$ is matrix-multiplication.
- Each arrow $m \stackrel{A}{\longleftarrow} n$ tells that matrix A has *n*-columns and *m*-rows.
- We say *n* is the **input** type of *A* and *m* the **output** type.
- Every **identity** $n \stackrel{id}{\leftarrow} n$ is the 1-diagonal of size n.
- Arrows (matrices) of types n < A 1 and 1 < A are known as (respectively) column and row vectors.



A category \mathbb{C} is a mathematical structure made of **arrows** between **objects** (the end-points of arrows) where

- The set of arrows between two objects m and n is denoted by $\mathbb{C}(m, n)$.
- Writing $n \stackrel{a}{\longleftarrow} m$, $m \stackrel{a}{\longrightarrow} n$ or $a \in \mathbb{C}(m, n)$ means the same.
- Given arbitrary arrows $b \in \mathbb{C}(k, n)$ and $a \in \mathbb{C}(m, k)$, the composite arrow $b \cdot a$ always exists and belongs to $\mathbb{C}(m, n)$.
- The **identity** arrow $n \xrightarrow{id} n$ always exists, for each object n.
- Composition is associative (1) with *id* as unit (2).

Arrows are often called **morphisms**. $\mathbb{C}(m, n)$ are termed **homsets**.



Category	Objects	Arrows	Composition
\mathbb{N}	naturals	naturals	multiplication
\mathbb{M}	naturals	matrices	MMM
I	sets	\subseteq	see below

Note that the homset

- M (m, n) may contain an arbitrary number of matrices
- N (m, n) contains either none or just one natural number, n/m if it exists
- I (*A*, *B*) contains either none or just one arrow, which we have denoted by ⊆; thus **composition** chains two ⊆ facts.



Next we add to the group the very well-known **category** S of **sets** and **functions** between sets — for many people, the category "par excellence":

Category	Objects	Arrows	Composition
N	naturals	naturals	multiplication
\mathbb{M}	naturals	matrices	MMM
I	sets	\subseteq	see above
S	sets	functions	function composition

Category S is the theoretical basis of **functional programming**.

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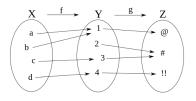
The details of S are given in the following slide.



In the S category,

- the identity A ^{id} → A in S is the copy-the-input function id (a) = a;
- arrow composition

 $X \xrightarrow{f} Y \xrightarrow{g} Z \text{ is the expected}$ $(g \cdot f) (x) = g (f (x))$ pictured aside.



 $(g \cdot f) x = g (f x)$

Homset S(X, Y) is the set of all (total) functions from X to Y.



Some programming languages implement category $\mathbb S$ in a rather simple way, notably Haskell:

```
Prelude> :type id
id :: a -> a
Prelude> :type (.)
(.) :: (b -> c) -> (a -> b) -> a -> c
```

Thus, for instance,

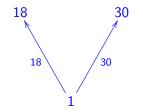
```
Prelude> id "Hello"
"Hello"
Prelude> id 3
3
Prelude> (sqrt . succ) 3
2.0
```

(But be warned that full Haskell requires more than category S.)

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Back to category \mathbb{N} , consider the following diagram:



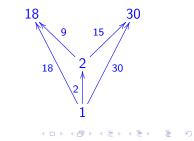
Fine, since 1 indeed divides any number.

In category theory (CT) jargon, we say that 1 is **initial** in \mathbb{N} . This means that

there **always** is **exactly one** arrow from 1 to any n.

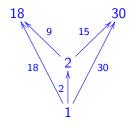
Diagram tells that 1 is a **common divisor** of 18 and 30.

But not the only one, check e.g.





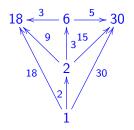
The diagram



tells that 2 is also a common divisor, and a larger one.

How far can we go towards **larger** common divisors?

Still another larger one, 6,



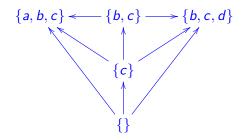
but no more — 6 is the greatest common divisor (gcd) between 18 and 30: gcd (18, 30) = 6

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A similar situation — e.g. diagram of the same shape — but in the set inclusion category I (omitting the \subseteq label in each arrow):



In this case,

 $\{b, c\} = \{a, b, c\} \cap \{b, c, d\}$

is the greatest common subset — known as intersection.



Note how both 6 = gcd (18, 30) and $\{b, c\} = \{a, b, c\} \cap \{b, c, d\}$ are **limit** objects — you cannot find **larger** objects fitting in the diagrams.

To understand the name given in CT jargon to such limit objects,

$$\{a, b, c\} \longleftarrow \{a, b, c\} \cap \{b, c, d\} \longrightarrow \{b, c, d\}$$

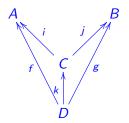
and

$$18 \stackrel{3}{\longleftarrow} \underbrace{gcd(18,30)}_{6} \stackrel{5}{\longrightarrow} 30$$

we will play once again with the same "V"-shaped arrow pattern, this time in the category S of sets — next slide.



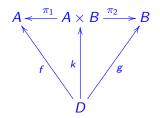
In \mathbb{S} , two pairs of functions f, g and i, j fitting in a diagram with the "V"-topology:



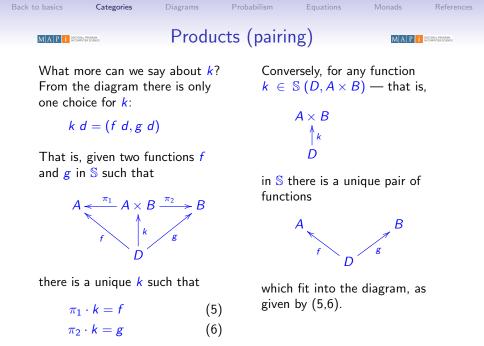
Assuming $k: D \rightarrow C$ fits in the diagram too.

k "factors" **both** f and g.

The "limit factorization" of fand g occurs when $C = A \times B$, the Cartesian product of A and B,

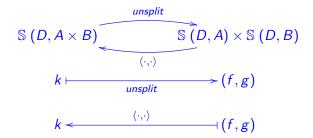


for $i = \pi_1, j = \pi_2$, the two projections $\pi_1 (a, b) = a$ and $\pi_2 (a, b) = b$.





Thus, there is a **bijection** between *pair-valued* functions and *pairs* of functions,



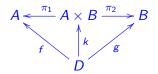
where *unsplit* $k = (\pi_1 \cdot k, \pi_2 \cdot k)$.

Below we will prefer the "outfix" notation $k = \langle f, g \rangle$ instead of "prefix" notation $k = \langle f, g, \cdot \rangle$.



Another way of capturing the same bijection is to write the **universal** property:

$$k = \langle f, g \rangle \quad \Leftrightarrow \quad \left\{ \begin{array}{c} \pi_1 \cdot k = f \\ \pi_2 \cdot k = g \end{array} \right. \tag{7}$$

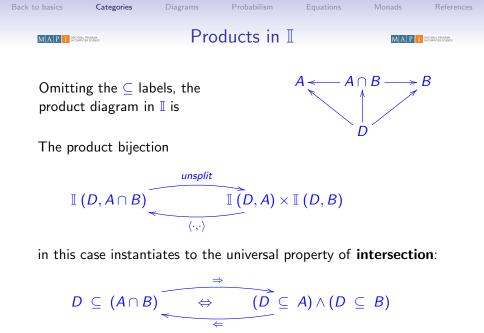


Interpret (7) as explained on the right.

Given f and g as in the diagram,

- (⇒) existence

 there is
 always some k
 fitting into the
 diagram
- (⇐) uniqueness such a k is unique.

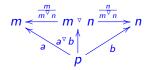


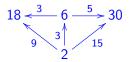
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Next, the same "V"-diagram and property in \mathbb{N} with an example, abbreviating gcd(x, y) by $x \lor y$:





Universal property:

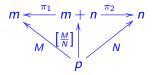
$$k = a \lor b \iff \begin{cases} \frac{m}{m^{\triangledown}n} \cdot k = a \\ \frac{n}{m^{\triangledown}n} \cdot k = b \end{cases}$$

Corollary $(k = a \lor b)$:

$$\frac{m}{a} = \frac{n}{b} = \frac{m \, {}^{\vee} \, n}{a \, {}^{\vee} \, b}$$



Finally, still the same "V"-shape and property, now in \mathbb{M} :



NB: $\begin{bmatrix} M \\ N \end{bmatrix}$ is the vertical stacking of two matrices *M* and *N* with the same number of columns *p*.

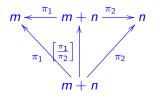
Universal property:

$$X = \begin{bmatrix} M \\ \overline{N} \end{bmatrix} \quad \Leftrightarrow \quad \left\{ \begin{array}{c} \pi_1 \cdot X = M \\ \pi_2 \cdot X = N \end{array} \right. \tag{8}$$

What kind of matrices are π_1 and π_2 ? (Next slide)



Consider this instance of the diagram:



Necessarily,

$$\left[\frac{\pi_1}{\pi_2}\right] = id \qquad (9)$$

because of uniqueness.

Don't buy this argument?

Take the universal property,

$$X = \begin{bmatrix} \frac{M}{N} \end{bmatrix} \quad \Leftrightarrow \quad \left\{ \begin{array}{l} \pi_1 \cdot X = M \\ \pi_2 \cdot X = N \end{array} \right.$$

for X = id and solve it for M and N. You get $M = \pi_1$ and $N = \pi_2$.

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References

Products in \mathbb{M}

Equality (9) tells that π_1 and π_2 are complementary **fragments** of the identity matrix, for example $2 \leftarrow \frac{\pi_1}{2} + 3 \xrightarrow{\pi_2} 3$ in MATLAB:

>> p1(2,3)					>>	>> [p1(2,3) ; p2(2,3)]]					
	1	0	0	0	0				1	0	0	0	0	
	0	1	0	0	0				0	1	0	0	0	
									0	0	1	0	0	
>> p2(2,3)						0	0	0	1	0				
									0	0	0	0	1	
	0	0	1	0	0									
	0	0	0	1	0									
	0	0	0	0	1									

 π_1 , π_2 and *id* are examples of **Boolean** matrices — they contain either 0s or 1s.



Suppose one wants to investigate what it means to **reverse** the arrows of a diagram. Does it make sense? What does one get?

In M, each arrow $m \xrightarrow{M} n$ can be converted into the reverse arrow $m \xrightarrow{M^{\circ}} n$ known as the **converse** or **transpose** of *M*, such that

$$(M \cdot N)^{\circ} = N^{\circ} \cdot M^{\circ}$$

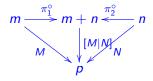
$$(M^{\circ})^{\circ} = M$$

$$(11)$$

Clearly, M° is M with rows swapped with columns.



The converse of a **product** diagram in \mathbb{M} is a so-called **coproduct** diagram,



NB: [M|N] is the **horizontal** gluing of two matrices M and N with the same number of rows p.

Universal property:

$$X = [M|N] \quad \Leftrightarrow \quad \begin{cases} X \cdot i_1 = M \\ X \cdot i_2 = N \end{cases}$$
(12)

where $i_1 = \pi_1^{\circ}$ and $i_2 = \pi_2^{\circ}$ are known as **injections**.



Terminology:

Read $\begin{bmatrix} M \\ N \end{bmatrix}$ as "M split N" and [M|N] as "M junc N". Duality:

$$[M|N]^{\circ} = \left[\frac{M^{\circ}}{N^{\circ}}\right]$$
(13)

Exchange law:

$$\left[\left[\frac{M}{N}\right] \mid \left[\frac{P}{Q}\right]\right] = \left[\frac{[M|P]}{[N|Q]}\right]$$
(14)

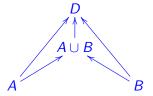
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(More in the sequel.)

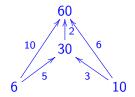


This duality in \mathbb{M} is quite strong and is called **self duality**. In other categories the objects involved may change.

In \mathbb{I} , **coproducts** correspond to set **union**, cf.



In \mathbb{N} , coproducts correspond to **least common multiple**, cf.



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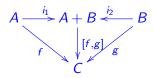
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Universal properties

 $(A \cup B) \subseteq D \iff A \subseteq D \land B \subseteq D$



The coproduct diagram in S:



NB: A + B is the **disjoint union** of A and B under injections $i_1 a = (1, a)$ and $i_2 b = (2, b)$; the intuitive meaning of [f, g]will be given later.

Universal property:

$$k = [f,g] \quad \Leftrightarrow \quad \left\{ \begin{array}{l} k \cdot i_1 = f \\ k \cdot i_2 = g \end{array} \right. \tag{15}$$

Combinator [f, g] hides a kind of "if-then-else": either f or g to run depending on the type of the input.

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Given a **predicate** $A \xrightarrow{p} Bool$, define

$$p?: A \to A + A$$
$$p? a = \begin{cases} i_1 \ a \Leftarrow p \ a \\ i_2 \ a \Leftarrow \neg p \ a \end{cases}$$

Then arrow composition grants the existence of **conditional** arrows:

if p then f else $g = [f,g] \cdot p$?

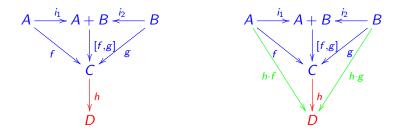
These arrows are of the same type as their arguments f, g.

(Note how we are getting closer and closer to having a **programming language**...)



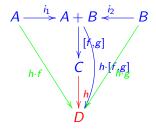
The **existence** and **uniqueness** of arrow k in (15) offers a nice, diagrammatic way of calculating properties.

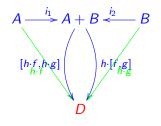
For instance, adding another arrow h to the coproduct diagram entails, by **existence**:





Still existence:





Next, by uniqueness:

 $h \cdot [f,g] = [h \cdot f, h \cdot g]$

(16)

This is known as the coproduct-fusion law.



A similar sequence of diagrams will yield the product-fusion law

 $\langle f,g\rangle \cdot h = \langle f \cdot h,g \cdot h \rangle$

in S, etc. Most importantly:

Due to the **abstract equivalence** of all product or co-product diagrams, we can port these properties from \$ to other categories, e.g. the **gcd**-fusion law in ℕ,

 $(a \lor b) \cdot c = (a \cdot c) \lor (b \cdot c)$

the two fusion laws of blocked linear algebra in $\ensuremath{\mathbb{M}}$,

$$\begin{bmatrix} \frac{M}{N} \end{bmatrix} \cdot Q = \begin{bmatrix} \frac{M \cdot Q}{N \cdot Q} \end{bmatrix}$$
(18)
$$Q \cdot [M|N] = [Q \cdot M|Q \cdot N]$$
(19)

(17)

and so on and so forth.



Summing up:

- Saving one's brain is perhaps the most **practical** outcome of CT: a single, **generic** construct instantiates to many semantically disparate concrete constructs.
- A single proof (using **diagrams**, if you like) replaces many repetitive proofs at instance level.
- **Products** and **coproducts** are themselves instances of more general constructs known as **limits** and **colimits** (cf. later in the course).
- A single, unified and typed (arrow) language for all domains.

More about this next.



The objects of \mathbb{M} can be generalized from numeric dimensions $(n, m \in \mathbb{N}_0)$ to arbitrary denumerable sets (types) (X, Y), taking

- disjoint union X + Y for m + n,
- Cartesian product $X \times Y$ for $m \times n$
- Any (fixed) singleton type 1 for number $1 \in \mathbb{N}$.

Matrix multiplication — **composition** in \mathbb{M} — is still well-defined since addition is commutative, so the order in the summation

$$y (M \cdot N) x = \langle \sum z :: (y M z) \times (z N x) \rangle$$
 (20)

is irrelevant.

NB: note that the (b, a)-cell of matrix M is denoted by b M a and not by $M_{b,a}$ or any other notation. (The rationale behind this choice of notation will be explained later.)



Are the categories we have seen completed isolated worlds?

No — we can relate/combine them. Let us show, as example, how S can be expressed in (generalized) M.

Think of a function $f : A \to B$ in \mathbb{S} and check how it can be represented by a matrix $M : A \to B$ in \mathbb{M} , say

 $M = \llbracket f \rrbracket$

defined by

$$b \llbracket f \rrbracket a = \begin{cases} 1 \text{ if } b = (f a) \\ 0 \text{ otherwise} \end{cases}$$
(21)



Example: the function in S

$$Bool \xrightarrow{\neg} Bool = \begin{cases} \neg False = True \\ \neg True = False \end{cases}$$

is represented in ${\mathbb M}$ by the matrix

$$Bool \xrightarrow{\llbracket \neg \rrbracket} Bool = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

- a representation we use all the time, albeit "informally".

The same matrix with the typing made explicit:

 $Bool \xrightarrow{[[\neg]]} Bool = \frac{False \quad True}{False \quad 0 \quad 1}$ $True \quad 1 \quad 0$



Moreover, everything we can do in $\mathbb S$ can be done in $\mathbb M,$ for instance composition

 $\llbracket f \cdot g \rrbracket = \llbracket f \rrbracket \cdot \llbracket g \rrbracket$

with **identity** $[\![id]\!] = id$ — cf. the following check in MATLAB that negation (\neg) is a bijection:

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```
>> not = [0 1; 1 0]
>> not * not
ans =
    1     0
    0     1
```



However, not every **matrix** in \mathbb{M} represents a **function** from \mathbb{S} .

Not even every **Boolean matrix** (containing zeros and ones only) represents a function, e.g.

 $M = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}$

Here we don't know which output for the first argument to choose, and for the second argument the "function" is **undefined**...

We say that S is a subcategory of M.

(This relationship will be later made more precise using so-called **functors** between categories.)



There is a nice way of checking whether a matrix represents a function on not.

Pick the **unique** function that one can think of, of type $A \rightarrow 1$ — (necessarily) a **constant** function.

This function is usually named "bang" (as it "destroys" every argument!) and written $!: A \rightarrow 1$.

A Boolean matrix $M : A \to B$ in \mathbb{M} uniquely represents a function of the same type $A \to B$ in \mathbb{S} iff $! \cdot M = !$ (22) holds.

Note the *polymorphism* of the two copies of !.



MATLAB: checking that matrix

 $M = 1 0 1 \\ 0 1 0$

represents a function:

>> [1 1] * M ans = [1 1 1]

You can see above two copies of the polymorphic "bang" matrix.

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QUESTION: What does clause (22) mean in case we relax the **Boolean** requirement and let M hold positive real numbers?

One easily checks that e.g. the following matrix,

 $M = \begin{bmatrix} 0.5 & 0.3 & 0 & 0.75 \\ 0.5 & 0.7 & 1 & 0.25 \end{bmatrix}$ satisfies (22).

Thus we have found another interesting **subcategory** of \mathbb{M} — that which includes all **probabilistic functions** (\mathbb{P}), instances of which are commonly known as **Markov chains**.

 \mathbb{S} is also a subcategory of \mathbb{P} — as "pure" functions correspond to restricting to **Dirac distributions** — one sole 1 per column.



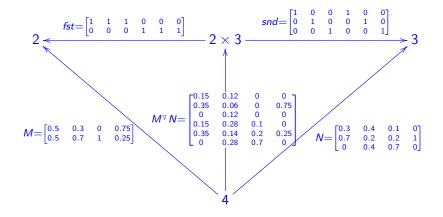
- What does a **morphism** of type $1 \longrightarrow A$ mean?
 - In \mathbb{N} , $1 \xrightarrow{n} n$ denotes the **number** *n* itself
 - In S, 1 → A means a point, since p can only yield one element (point) of A
 - In M, 1 → A is known as a column vector (matrix with only one column)

• In \mathbb{P} , $1 \xrightarrow{\delta} A$ is called a **distribution**, for instance

$$1 \xrightarrow{\delta} 6 = \begin{bmatrix} 0\\0.2\\0.2\\0.6\\0\\0\end{bmatrix}$$



What does **arrow pairing** mean in \mathbb{M} or \mathbb{P} ? Check the diagram:



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In \mathbb{M} (also \mathbb{P}) pairing corresponds to the so called **Khatri-Rao product** $A \times B \stackrel{M^{\vee}N}{\leftarrow} C$ of two matrices $A \stackrel{M}{\leftarrow} C$ and $B \stackrel{N}{\leftarrow} C$:

 $(a,b) (M \lor N) c = (a M c) \times (b N c)$ (23)

Example in MATLAB:

>> kr([1,0,11;-3,-4,0;], [0,1,3;0,2,4;]) ans =

0	0	33
0	0	44
0	-4	0
0	-8	0



This time there are differences, however, compared to S, as pairing in \mathbb{P} is not perfect:

$$X = M \circ N \quad \Rightarrow \quad \begin{cases} fst \cdot X = M \\ snd \cdot X = N \end{cases}$$
(24)

As (\Leftarrow) is not guaranteed, lossless decomposition may fail and

 $(fst \cdot X) \lor (snd \cdot X)$

differs from X in general.

We say that **pairing** in \mathbb{P} is a **weak**-product.

Note, however, that $[\![f]\!] \circ [\![g]\!] = [\![\langle f, g \rangle]\!]$, where f and g are "pure" functions.

Back to basics

Categories

iagrams

Probabilism

MART Probabilistic pairing (entanglement)

The problem is that reconstruction

 $X = (fst \cdot X) \lor (snd \cdot X)$

doesn't hold in general, cf. e.g.

X : 2	$2 \rightarrow 2$	2×3		Fo 24	0 47
	ΓΟ	0.4		0.24	0.4
		0.1		0.24	0
	0.2	0		0.08	0.1
<i>X</i> =	0.2	0.1	$(\mathit{fst} \cdot X) \circ (\mathit{snd} \cdot X) =$	0.08	0.4
<u> </u>	0.6	0 0.1 0.4			
		0		0.12 0.12	0
		~ 1		0.12	0.1
	0	0.1		L	_

X is not recoverable from its projections: Khatri-Rao not surjective.

In **quantum** computing this situation is known as **entanglement** — entangled distributions on pairs cannot be projected into pairs of distributions.



Consider the following instance of pairing, in S,

 $12 \stackrel{\text{add}}{\leftarrow} 6 \times 6 \stackrel{a^{\nabla} b}{\leftarrow} 1 \tag{25}$

where add(x, y) = x + y.

Clearly, the composition expresses the term a + b, since a and b stand for numbers in $\{1...6\}$.

What does the same diagram mean in \mathbb{P} ? In this case *a* and *b* are bound to be distributions.

One can think of a and b being two **dice** and of diagram (25) as expressing the **probability of the sum** of the faces shown (next slide).



Assume both dice are **fair**, that is, the input distributions are **uniform**:

 $a = b = \begin{bmatrix} \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} \end{bmatrix}^{\circ}$

Addition is represented by the matrix

 $y \llbracket add \rrbracket (a, b) = if y = a + b then 1 else 0$

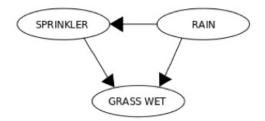
Then the arrow $12 < \frac{add \cdot (a^{\nabla} b)}{1}$ evaluates to the distribution aside, where outcome 1 is impossible, outcome 7 is the most likely, and so son.

0.0278 0.0555 0.0833 0.1111 0.1389 0.1667 0.1389 0.1389 0.0833 0.0555 0.0278



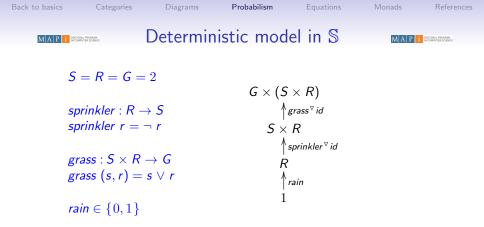
Example adapted from

[https://en.wikipedia.org/wiki/Bayesian_network]



Control a sprinkler to wet the grass in case it does not rain.

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Grass always wet:

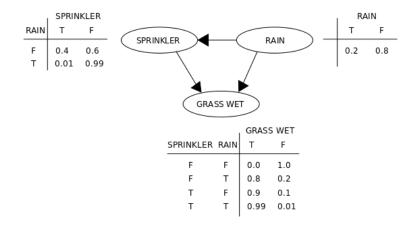
grass (sprinkler r, r) = $\neg r \lor r$ = True

Altogether, two possible states $\{(1, (1, 0)), (1, (0, 1))\}$ of type: $G \times (S \times R) \stackrel{state}{\longrightarrow} 1 = (grass \lor id) \cdot (sprinkler \lor id) \cdot rain$

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Previous model (in \mathbb{S}) is not realistic — the pictures actually found on Wikipedia are:





This corresponds to moving to \mathbb{P} and letting

$$S = R = G = 2
S < \frac{sprinkler}{S} R = \begin{bmatrix} 0.60 & 0.99 \\ 0.40 & 0.01 \end{bmatrix}$$

$$R < \frac{rain}{1} = \begin{bmatrix} 0.80 \\ 0.20 \end{bmatrix}$$

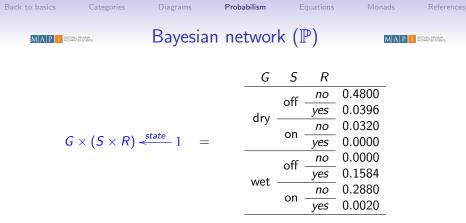
$$G < \frac{grass}{S} S \times R = \begin{bmatrix} 1.00 & 0.20 & 0.10 & 0.01 \\ 0 & 0.80 & 0.90 & 0.99 \end{bmatrix}$$

$$R < \frac{rain}{1} R$$

The "same" state arrow

 $G \times (S \times R) \stackrel{state}{\longleftarrow} 1 = (grass \lor id) \cdot (sprinkler \lor id) \cdot rain$

now has a different meaning since the category became \mathbb{P} (next slide).



Moreover, we can define

$$1 \xleftarrow{\text{grass_wet}} G \times (S \times R) = [0 \ 1] \cdot \text{fst}$$
$$1 \xleftarrow{\text{raining}} G \times (S \times R) = [0 \ 1] \cdot \text{snd} \cdot \text{snd}$$

etc. to obtain e.g. $P_{state}(grass_wet) = grass_wet \cdot state = 44.84\%$.



Conditional probabilities over a state distribution δ :

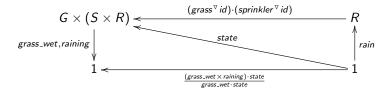
$$P_{\delta}(a \mid b) = \frac{(a \times b) \cdot \delta}{b \cdot \delta} \quad \text{given} \quad 1 \stackrel{a,b}{\longleftarrow} S \stackrel{\delta}{\longleftarrow} 1$$

(26)

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Boolean vectors *a* and *b* describe "event" sets.

Recall



Forwards: $P_{state}(grass_wet | raining) = 80.19\%$

Backwards: $P_{state}(raining | grass_wet) = 35.77\%$



Diagrams central to category theory.

They can express **abstract** properties or abstract **models** of problems.

A diagram modeling a problem captures its essence, or abstract structure.

Keeping the diagram, more elaborate semantics for the problem can be expressed **just** by changing category:

"Keep definition, change category" principle (Oliveira and Miraldo, 2016)

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Given two numbers a and b, we can add them (a + b), multiply them $(a \times b)$ etc.

Likewise, given two matrices $n \stackrel{M,N}{\leftarrow} m$ we can add them (M + N), e.g.

$$\left(\begin{array}{rrrr}1&0&0\\-9&3&12\\0&-1&0\end{array}\right)+\left(\begin{array}{rrrr}1&1&1\\2&3&4\\0&1&0\end{array}\right)=\left(\begin{array}{rrrr}2&1&1\\-7&6&16\\0&0&0\end{array}\right)$$

and multiply them $(M \times N)$:

$$\left(\begin{array}{rrrr}1&0&0\\-9&3&12\\0&-1&0\end{array}\right)\times\left(\begin{array}{rrrr}1&1&1\\2&3&4\\0&1&0\end{array}\right)=\left(\begin{array}{rrrr}1&0&0\\-18&9&48\\0&-1&0\end{array}\right)$$

But, matrices are **arrows** (morphisms) — does it make sense to "add / multiply arrows"?



Yes it does, in so-called **enriched**-categories: categories with **extra** mathematical **structure**.

Recall that a homset $\mathbb{C}(m, n)$ in a category \mathbb{C} is a set.

An **enrichment** consists in adding some algebraic structure to such sets.

Some care is needed concerning the interplay between such enriched $\mathbb{C}(m, n)$ and the basic structure, namely **composition**.

Abelian categories (next slide) are particularly interesting cases of enriched categories.



 \mathbb{M} is **Abelian** because every homset $\mathbb{M}(m, n)$ forms an additive Abelian group (**Ab**-category) such that composition is bilinear relative to +:

$$M \cdot (N+L) = M \cdot N + M \cdot L$$
(27)
(N+L) \cdot K = N \cdot K + L \cdot K (28)

The Abelian structure grants M + 0 = M, where 0 is the all-0 matrix of its type.

The Abelian structure can be further enriched to a ring with $M \times N$ given by the so-called **Hadamard** product:

 $b(M \times N) a = (b M a) \times (b N a)$ ⁽²⁹⁾

 $M \times 1 = M$ holds where 1 is the all-1 matrix of its type.

NB: as before we assume \mathbb{M} defined over the reals.



The additive structure of ${\mathbb M}$ grants a number of laws, namely the so called ${\rm divide}{-}{\rm and}{-}{\rm conquer}$ law

$$[M|N] \cdot \left[\frac{P}{Q}\right] = M \cdot P + N \cdot Q \tag{30}$$

which is the basis of $\left(\textbf{parallel} \right)$ blocked linear algebra, and can also be written as

$$[M|N] \cdot [P|Q]^{\circ} = M \cdot P^{\circ} + N \cdot Q^{\circ}$$
(31)

It turns out that

$$\begin{bmatrix} M | N \end{bmatrix} = M \cdot \pi_1 + N \cdot \pi_2$$
(32)
$$\begin{bmatrix} \frac{M}{N} \end{bmatrix} = i_1 \cdot M + i_2 \cdot N$$
(33)

also hold.



Categories can also be enriched by regarding homsets as ordered structures, for instance **partial orders**.

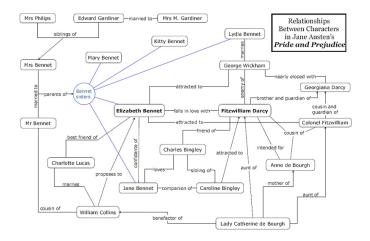
This is useful when we want to solve **recursive equations** in a category (more about this later).

The topic brings about another category — the category of **binary** relations \mathbb{R} .

This category is very useful to model real-life problems: relational **databases** rely on \mathbb{R} by definition.



... in real life - recall



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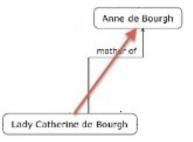


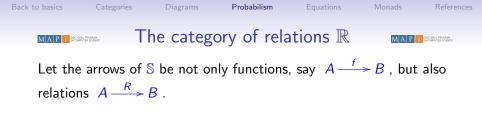
The picture is a collection of **relations** — aka. a **semantic network** — elsewhere known as a (binary) **relational system**.

However, in spite of the use of **arrows** in the picture (aside) not many people would write

mother_of : *People* \rightarrow *People*

as the **type** of **relation** *mother_of*.





In the same way assertion b = f a may hold or not, so may b R a, the assertion that pair (b, a) belongs to R.

Thus extended, \mathbb{S} becomes \mathbb{R} , the category of **binary relations**.

In \mathbb{R} , *id* is the **equality** relation; **composition** $R \cdot S$ is given by

 $b(R \cdot S) c \Leftrightarrow \exists a : b R a \land a S c$ (34)

cf.





In general, the **converse** f° of a function f is a relation, not a function.

Thus S does not have converse morphisms, while \mathbb{R} does: $a(R^{\circ}) b$ means the same as b R a — as in \mathbb{M} , recall.

Like in \mathbb{M} , we have the laws $(R \cdot S)^{\circ} = S^{\circ} \cdot R^{\circ}$ (35) $R^{\circ \circ} = R$ (36)

So \mathbb{R} is another example of a self-dual category. Arrows $A \to 1$ and $1 \to A$ both denote **sets**.



Category \mathbb{R} provides a useful generalization of \mathbb{S} .

A rich terminology emerges simply by defining the order

 $R \subseteq S \Leftrightarrow R \cup S = S \tag{37}$

on the homsets:

- *R* is **reflexive** iff $id \subseteq R$
- *R* is symmetric iff $R^\circ \subseteq R$
- *R* is **transitive** iff $R \cdot R \subseteq R$
- *R* is **injective** iff $R^{\circ} \cdot R \subseteq id$
- *R* is simple (aka. a partial function) iff $R \cdot R^\circ \subseteq id$
- *R* is entire (aka. total) iff $id \subseteq R^{\circ} \cdot R$
- *R* is surjective iff $id \subseteq R \cdot R^{\circ}$



Each homset $\mathbb{R}(A, B)$ forms a **Boolean algebra** under union (U), intersection (\cap) and complementation, plus a **topmost** relation $B \stackrel{\top}{\longleftarrow} A$ and a **least** relation $B \stackrel{\perp}{\longleftarrow} A$.

Pairing in \mathbb{R}

 $(a,b) (R \lor S) c = (a R c) \land (b S c)$ (38)

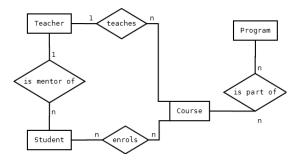
does not even form a weak-product. But its universal property takes advantage of the order-enriched structure:

 $\pi_1 \cdot X \subseteq R \land \pi_2 \cdot X \subseteq S \quad \Leftrightarrow \quad X \subseteq R \lor S \tag{39}$

(This is an example of a so-called **Galois** connection.)



So-called "Entity-Relationship" (ER) diagrams are commonly used to capture relational data schemas, e.g.¹



Draw the same using morphism (arrows) in \mathbb{R} and identify the properties of each relation in the diagram.

¹Credits: https://dba.stackexchange.com/questions.



If S supports functional programming, \mathbb{R} supports another programming paradigm: take the (simple) Prolog program

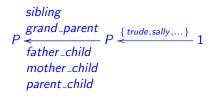
```
mother_child(trude, sally).
```

```
father_child(tom, sally).
father_child(tom, erica).
father_child(mike, tom).
parent_child(X, Y) :- father_child(X, Y).
parent_child(X, Y) :- mother_child(X, Y).
sibling(X, Y) :- parent_child(Z, X), parent_child(Z, Y).
```

grand_parent(X, Y) := parent_child(X, Z), parent_child(Z, Y).



Meaning of this program in category \mathbb{R} :



Clauses:

$mother_child \cup father_child \subseteq parent_child$	(40)
$parent_child^{\circ} \cdot parent_child \ \subseteq \ sibling$	(41)
$parent_child \cdot parent_child \subseteq grand_parent$	(42)

Note how object P (type for people) is made explicit (typing!).



Running query

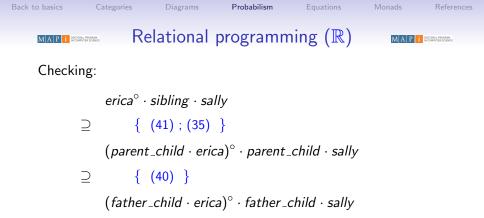
?- sibling(erica,sally)

cf. diagram



corresponds to checking whether arrow $1^{erica^\circ \cdot sibling \cdot sally}$ (a scalar in \mathbb{R}) is empty or not.

NB: *erica* and *sally* are atoms, therefore ("atomic") functions.



= { facts }

 $tom^{\circ} \cdot tom$

Т

 $= \{ tom is an atom \}$

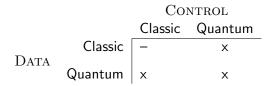


"Equation" a la Wirth:

(Quantum) Programs = (Quantum) Algorithms + (Quantum) Data Structures

Quantum algorithms based on elementary **components**, called **quantum gates**.

Classical bits generalize to quantum bits (\mathbf{qubits}) — quantum data.



Back to basics

MAPI we what about quantum programming?

In quantum programming, all computations are reversible.

This is expressed in linear algebra by so-called **unitary** matrices.

Standard quantum programming gates, used in quantum circuits (Nielsen and Chuang, 2011) can be expressed in \mathbb{M} , that is, in typed LA.

They can be **decomposed** into polymorphic, elementary matrix categorial **units**.

Pairing (Khatri-Rao ${}^{_\nabla}$ + Kronecker products $\otimes)$ is central to quantum data structuring.

From now on we extend matrices in \mathbb{M} to hold **complex** numbers (\mathbb{C}) ans not just reals.



A \mathbb{C} -valued matrix U is unitary iff $U \cdot U^* = U^* \cdot U = id$, where U^* is the **conjugate** transpose of U.

Thus all isomorphisms (reversible functions) are special cases of **unitary** matrices.

But **isomorphisms** admit further decompositions in terms of such matrices, for instance "the sqrt of not"

 $\neg = (\sqrt{\neg}) \cdot (\sqrt{\neg})$

where

$$\sqrt{\neg} = \frac{1}{2} \left(\top + i \left(id - \gamma \right) \right) = \frac{1}{2} \begin{bmatrix} 1+i & 1-i \\ 1-i & 1+i \end{bmatrix}$$

Thus one gets into the wonderful world of **actual** quantum gates in which classical logic operations are no longer primitive.



Quantum application — like function application, the outcome of processing quantum data s by quantum gate P is given by $P \cdot s$.



Qubits — The smallest (useful) *A* is 2, the Booleans — so a (qu)bit $2 < \frac{s}{b} = 1$ is always a vector of the form $\begin{bmatrix} a \\ b \end{bmatrix}$.

'Ket' Notation — traditionally,

- $|0\rangle: 1 \to 2$ denotes the vector $\begin{bmatrix} 1\\ 0 \end{bmatrix}$ which represents point $\underline{0}$ (a bit holding 0).
- $|1\rangle: 1 \rightarrow 2$ denotes the vector $\begin{bmatrix} 0\\1 \end{bmatrix}$ which represents point <u>1</u> (a bit holding 1).



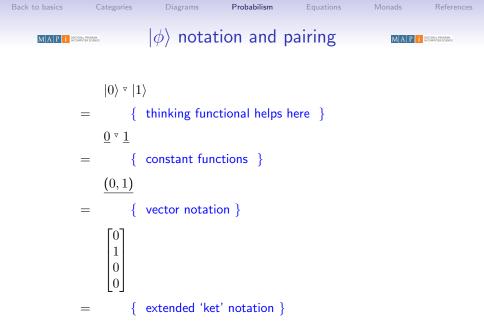
Since $\begin{bmatrix} a \\ b \end{bmatrix} = a \begin{bmatrix} 1 \\ 0 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \end{bmatrix}$, the notation $a |0\rangle + b |1\rangle$ is normally used to denote **qubit** $\begin{bmatrix} a \\ b \end{bmatrix}$.

A qubit $2 < \frac{a |0\rangle + b |1\rangle}{1}$ expresses a quantum **superposition** of the two truth values.

Complex numbers $a, b \in \mathbb{C}$ are called **amplitudes** and are such that $a^2 + b^2 = 1$.

Given two qubits $1 \xrightarrow{u} 2$ and $1 \xrightarrow{v} 2$, $1 \xrightarrow{u^{\vee} v} 2 \times 2$ denotes their **pairing**.

This leads to an extension of the 'ket' notation (next slide).



 $|01\rangle$



More generally, the qubit pairing $(a |0\rangle + b |1\rangle) \vee (c |0\rangle + d |1\rangle)$ yields, once converted to vector notation

$$\begin{bmatrix} \frac{a}{b} \end{bmatrix} \nabla \begin{bmatrix} \frac{c}{d} \end{bmatrix}$$

$$= \{ Khatri-Rao \}$$

$$\begin{bmatrix} ac \\ ad \\ bc \\ bd \end{bmatrix}$$

$$= \{ vector addition \}$$

$$\begin{bmatrix} ac \\ 0 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ ad \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ bc \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \\ bd \end{bmatrix}$$
is, $ac |00\rangle + ad |01\rangle + bc |10\rangle + bd |11\rangle$.

that



 $2 \times 2 \xleftarrow{\frac{|00\rangle + |01\rangle}{\sqrt{2}}} 1$

is a well-known example of entaglement - you get

 $\begin{aligned} & \textit{fst} \cdot \left(\frac{|00\rangle + |01\rangle}{\sqrt{2}}\right) = \left(\frac{|0\rangle + |1\rangle}{\sqrt{2}}\right) \\ & \textit{snd} \cdot \left(\frac{|00\rangle + |01\rangle}{\sqrt{2}}\right) = \left(\frac{|0\rangle + |1\rangle}{\sqrt{2}}\right) \end{aligned}$

but

$$\frac{|0\rangle+|1\rangle}{\sqrt{2}} \sqrt[]{} \frac{|0\rangle+|1\rangle}{\sqrt{2}} = 2 \times 2 \stackrel{\left(\frac{1}{2}\right)^{\circ}}{\checkmark} 1$$

is different from the original $2 \times 2 \stackrel{|00\rangle+|01\rangle}{\checkmark} 1$.

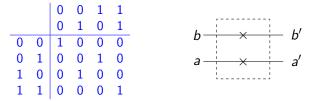


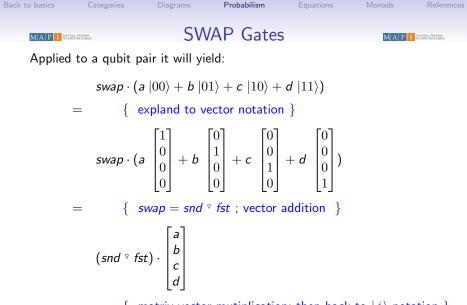
(Polymorphic) functional programming can play a nice role in quantum processing (perhaps not fully appreciated yet).

Think of the function swap (a, b) = (b, a), that is, the **isomorphism**:

 $A \times B \xrightarrow{swap} B \times A = snd \, \forall \, fst.$

For A = B = 2, this corresponds to the classical gate





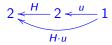
 $= \begin{cases} matrix-vector mutiplication; then back to <math>|\phi\rangle$ notation } $a |00\rangle + c |01\rangle + b |10\rangle + d |11\rangle \end{cases}$



A well-known quantum gate is the Hadamard gate:

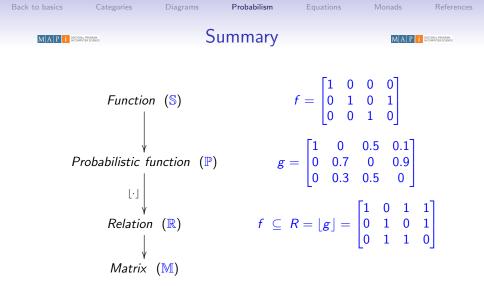
$$2 \stackrel{H}{\longleftarrow} 2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1\\ 1 & -1 \end{bmatrix}$$

Applying this gate to qubit $u = a |0\rangle + b |1\rangle$:



Calculation:

$$\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1\\ 1 & -1 \end{bmatrix} \cdot \left(\mathbf{a} \left| 0 \right\rangle + \mathbf{b} \left| 1 \right\rangle \right) = \frac{1}{\sqrt{2}} \left(\begin{bmatrix} 1 & 1\\ 1 & -1 \end{bmatrix} \cdot \begin{bmatrix} \mathbf{a} \\ \mathbf{b} \end{bmatrix} \right) = \frac{1}{\sqrt{2}} \left[\frac{\mathbf{a} + \mathbf{b}}{\mathbf{a} - \mathbf{b}} \right] = \frac{\mathbf{a} + \mathbf{b}}{\sqrt{2}} \left| 0 \right\rangle + \frac{\mathbf{a} - \mathbf{b}}{\sqrt{2}} \left| 1 \right\rangle.$$



 $\lfloor g \rfloor$ is called the **support** of *g*. Supports "convert" probabilistic functions into relations. Matrices in \mathbb{M} can be unitary.



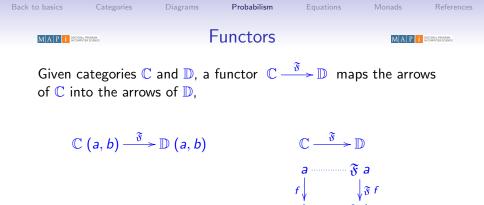
What is the **exact** meaning of the word "convert" in the previous slide?

This question also arises about matrix $[\![f]\!]$ (in category \mathbb{M}) "representing" function f in category \mathbb{S} .

The type of [-] should be something like $\mathbb{S} \to \mathbb{M}$.

But \mathbb{S} and \mathbb{M} are **categories**, not mere **sets**.

This raises the need for ${\bf functors}$ — functions which "map arrows to arrows".



such that

 $\mathfrak{F} id = id$ $\mathfrak{F} (g \cdot f) = (\mathfrak{F} g) \cdot (\mathfrak{F} f)$ (43) (43)

So \mathfrak{F} "respects" the core structure of categories: **identity** and **composition**.



A well-known example of a functor in \mathbb{S} , dear to **functional programming**, is the operation which **maps** a function f over a list, $\mathfrak{F} = f^*$ where $f^* x = [f \ a \ a \leftarrow x]$, cf. the diagram



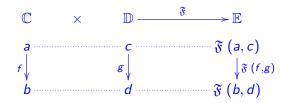
Clearly, (43) and (44) hold for this functor, that is,

$$id^* x = x$$
$$(g^* \cdot f^*) x = [(g \cdot f) a \mid a \leftarrow x] = (g \cdot f)^*$$

hold. Functor $_^* : \mathbb{S} \to \mathbb{S}$ is an example of a **endo**-functor — a functor from a category to itself.



Given in general three categories \mathbb{C} , \mathbb{D} and \mathbb{E} , a **bifunctor** $\mathbb{C} \times \mathbb{D} \xrightarrow{\mathfrak{F}} \mathbb{E}$ is a binary functor



such that:

 $\mathfrak{F}(id, id) = id \tag{45}$ $\mathfrak{F}(h \cdot f, k \cdot g) = \mathfrak{F}(h, k) \cdot \mathfrak{F}(f, g) \tag{46}$



$$M \oplus N = \begin{bmatrix} M & 0 \\ 0 & N \end{bmatrix}$$

is an (endo)bifunctor defined by

 $M \oplus N = [i_1 \cdot M | i_2 \cdot N]$

(48)

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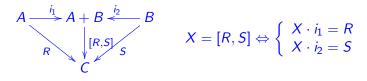
(47)

cf. the coproduct diagram



Direct sum

Notably, direct sum (48) is present in all categories \mathbb{M} , \mathbb{S} and \mathbb{R} , as coproducts of \mathbb{S} lift to coproducts in \mathbb{R} :



Kronecker product

Also interesting is the fact that, in spite of not being a product, **pairing** in \mathbb{M} leads to a bifunctor,

 $M \otimes N = M \cdot fst \, \overline{} \, N \cdot snd \tag{49}$

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known as **Kronecker product**, which also extends to \mathbb{S} and \mathbb{R} .



As expected, functors compose with each other.

The most simple functors are the **identity** functor, which maps an arrow onto itself,

 $\Im \left(b \stackrel{f}{\longleftarrow} a \right) = b \stackrel{f}{\longleftarrow} a$

and so-called **constant** functors: given an object k of a category \mathbb{C} , we define the constant functor \mathfrak{K} as

$$\Re\left(b \stackrel{f}{\leftarrow} a\right) = k \stackrel{id}{\leftarrow} k$$

In \mathbb{M} we will be particularly interested in the composite functor

 $\mathfrak{M} M = id \oplus M$

which will be present in examples to follow.



Recall where we started from (broad picture):

- Divisibility ordering in ℕ as example of a **reflexive** and **transitive** orders (**preorders**)
- We replaced each ordered pair by an arrow (witness)
- Thus preorders were "lifted" to categories.

In the same trend,

 what is the "lifting" of the concept of a monotone function between preorders, a ≤ b ⇒ (f a) ⊑ (f b)?

Well, we've just studied it:

Functors between categories generalize monotone functions between preorders.



Functors make it possible to think of solving **equations** in a categorial setting.

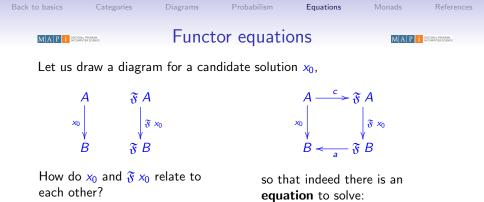
Starting point: we know that, given a **monotonic** function f we have techniques for solving the equation

x = f x

Above we have seen that **monotonic** functions between ordered structures scale up to **functors** between categories. So, what does the "categorial lifting" of x = f x,

 $x = \mathfrak{F} x$

yield? Note that, in the CT setting, any solution to $x = \mathfrak{F} x$ is bound to be an **arrow**: what kind of arrow?

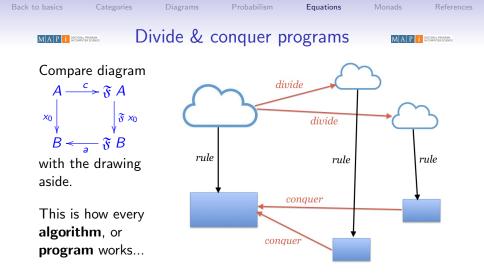


We need to "bridge" them up,

 $x_0 = a \cdot (\mathfrak{F} x_0) \cdot c$

In S, x_0 can be regarded as a recursive morphism — a program.

Questions: given *a* and *c*, does x_0 always exist? Is there a unique solution to $x_0 = a \cdot (\mathfrak{F} x_0) \cdot c$?



(Dictionary) **Divide & rule** — "the policy of maintaining control over subordinates by encouraging dissent between them".



In the \mathbb{R} category:

As homsets form a complete Boolean algebras in $\mathbb R,$ for monotonic $\mathfrak F$ the equation

 $x = a \cdot (\mathfrak{F} x) \cdot c$

always has a least solution (Knaster-Tarski fixpoint theorem) termed hylomorphism and denoted by [a, c].

In the S category:

S is not so flexible because solutions have to be **total** functions. But for particular **a** and **c** we can find standard solutions in S termed **catamorphisms** and **anamorphisms**, as explained below.



Terminology: in the equation



- $B \stackrel{a}{\longleftarrow} \mathfrak{F} B$ is referred to as an \mathfrak{F} -algebra
- $A \xrightarrow{c} \mathfrak{F} A$ is referred to as an \mathfrak{F} -coalgebra.

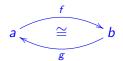
We will understand this terminology in a minute.

Before this, let us be aware that some \mathfrak{F} -(co)algebras are rather special.



A morphism $a \xrightarrow{f} b$ in a category \mathbb{C} is an **isomorphism** if it has a "two-sided" inverse, namely another morphism $a \xleftarrow{g} b$ in the same category such that $g \cdot f = id$ and $f \cdot g = id$.

One way of recording such an isomorphism is by drawing



It can be shown that the isomorphisms in \mathbb{R} , for instance, are the functions whose converses are also functions — the so-called **bijections**.



To understand all this terminology, let us see an example in \mathbb{R} .

Take Peano's (1858-1932) definition of the natural numbers (\mathbb{N}_0) :

- 0 is a natural number
- n+1 is a natural number once n is so
- there are no more natural numbers.

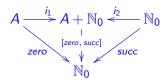
We thus have a constant $0 \in \mathbb{N}_0$ and a natural number "factory" succ : $\mathbb{N}_0 \to \mathbb{N}_0$ such that succ n = n + 1.

0 can be represented by the constant function *zero* x = 0, of type *zero* : $A \rightarrow \mathbb{N}_0$, for some non-empty set A.

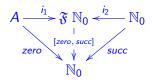
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Also note that *zero* and *succ* together generate a coproduct diagram:



Let us define functor $\mathfrak{F} X = A + X$, constant in A: $\mathfrak{F} f = id \oplus f$. Re-draw the diagram using \mathfrak{F} :

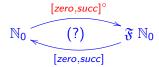


Thus [*zero*, *succ*] is an \mathfrak{F} -algebra.

Yes! it packs the algebraic operators of \mathbb{N}_0 into a single arrow.



The same algebra, rotated 90 degrees (in \mathbb{R} , cf. converse):



Question: is [zero, succ] an isomorphism?

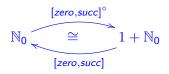
It is surjective — "there are no more natural numbers..."

• It is **not injective** — the *A* inputs are all ignored!

Clearly: it would be injective had A only one element...



So we choose A = 1. Recall that 1 denotes a set with only one element (predefined, not relevant which one in particular).



By the way, object 1 discriminates S from both \mathbb{R} and \mathbb{M} : the homset S(A, 1) is a singleton, a constant function which we have denoted by $!: A \to 1$.

In \mathbb{R} the homset $\mathbb{R}(A, 1)$ contains many relations, all below !.

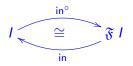
In \mathbb{M} the homset $\mathbb{M}(A, 1)$ contains all row vectors with |A|-many columns.



Back to diagram

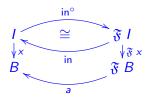
 $\begin{array}{c} A \xrightarrow{c} \mathfrak{F} A \\ \times \\ \downarrow \\ B \xleftarrow{a} \mathfrak{F} B \end{array}$

suppose **coalgebra** $c := in^{\circ}$ exists as an isomorphism over the smallest possible object A := I:



In this case, solution x**uniquely** depends on algebra

а,



and we write (*|a*|) to denote it in the corresponding **universal** property:

 $x = (|a|) \iff x \cdot in = a \cdot \mathfrak{F} x$



Back to diagram

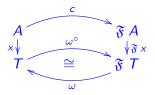


suppose **algebra** $a := \omega$ exists as an isomorphism over the largest possible B := T:



In this case, solution x

uniquely depends on coalgebra *c*,



and we denote it by [(c)] in the corresponding **universal** property:

 $x = \llbracket a \rrbracket \quad \Leftrightarrow \quad x \cdot \omega^{\circ} = c \cdot \mathfrak{F} x$

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- Programs can be of three different kinds, catamorphisms, anamorphisms or hylomorphisms.
- In ℝ, initial 𝔅-algebra / coincides with terminal 𝔅-algebra T and therefore the category has hylomorphisms,

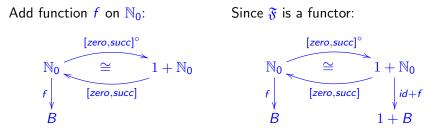
 $\llbracket a, c \rrbracket = (\lvert a \rvert) \cdot \llbracket c \rrbracket$

- In S, initial ℑ-algebra *I* is smaller than terminal ℑ-algebra *T*, and so [[*a*, *c*]] = (|*a*]) · [(*c*)] is not always defined.
- P is "half way" between R and S, but we need to study still another concept that of a **monad** to understand the relation between S and such categories.

Before this, some examples to help understand why the diagrams above are regarded as **programs**.



As earlier on, we play the game of adding arrows to diagrams and seeing what happens:

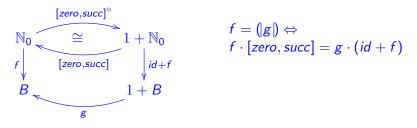


We can close the diagram provided we add another (1+)-algebra from 1 + B to B (next slide).

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Thus our first (recursive, but still abstract) program is born:



Note that $g = [g_1, g_2]$, since it mediates a sum: $g_1 : 1 \rightarrow B$ will tell how the program **stops** while $g_2 : B \rightarrow B$ calls for **further** iterations.

An instance of this schema follows in the next slide.



Example: let g = [zero, (n+)], where (n+) x = n + x, as expected. Then, using the universal property,

$$f = (|g|) \iff f \cdot [zero, succ] = [zero, (n+)] \cdot (id + f)$$

$$\Leftrightarrow \qquad \{ \text{ fusion and absorption (coproducts in S or } \mathbb{R}) \}$$

$$[f \cdot zero, f \cdot succ] = [zero, (n+) \cdot f]$$

$$\Leftrightarrow \qquad \{ \text{ coproduct equality} \}$$

$$\begin{cases} f \cdot zero = zero \\ f \cdot succ = (n+) \cdot f \end{cases}$$

Clearly, $f = (n \times)$. That is, we've synthesized the functional program

$$n \times 0 = 0$$

$$n \times (m+1) = n + n \times m$$

the same as: $n \times m = (\text{if } m = 0 \text{ then } 0 \text{ else } n + n \times (m - 1)).$



Another way to write the same program would be

 $(n \times) =$ for (n+) 0

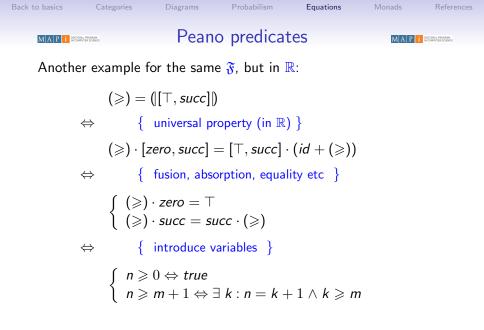
by introducing a suggestive shorthand combinator

for $g \ k = ([\underline{k}, g])$

where $\underline{k} = k$ denotes the constant function yielding k.

EXAMPLE in Haskell:

*Nat> let mul n = for (n+) 0 *Nat> mul 34 23 782



Cf. primitive induction.



So far we have been able to encode, in instances of the CT framework, **neat** constructs and **elegant** programs.

What about **"dirty"** programs, that is, those which produce **side-effects** ?

What about imperative ones?

And what about "faulty" programs, that is, those which misbehave, e.g. because they run on defective hardware?

We need another CT concept, and a very relevant one — that of a **monad**. Our last topic in this module.



"Monads [...] come with a curse. The monadic curse is that once someone learns what monads are and how to use them, they lose the ability to explain it to other people"

(Douglas Crockford: Google Tech Talk on how to express monads in JavaScript, 2013)



Douglas Crockford (2013)

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(https://www.youtube.com/watch?v=b0EF0VTs9Dci)



Some patterns of arrow **composition** don't work because the output are " \mathfrak{F} -times" more complex than expected, e.g.

$$\begin{array}{c}
\mathfrak{F} B \stackrel{g}{\leftarrow} A \\
\mathfrak{F} C \stackrel{f}{\leftarrow} B
\end{array}$$
(50)

Let e.g. $\mathfrak{F} B = E + B$ record the fact that g fails for some outputs, raising an **exception** in E, otherwise yielding a B.

In general, $\mathfrak{F} B$ (and $\mathfrak{F} C$ etc) carry some information about a **computational effect** which we have to **handle** but would like (technically) to **ignore**...



Declare in Haskell (S):

```
g a = [a+1, a-1]
f a = [\sqrt{a}, -\sqrt{a}]
```

This defines two arrows:

 $g :: Num \ t \Rightarrow t \rightarrow [t]$ $f :: Floating \ t \Rightarrow t \rightarrow [t]$

which do not compose. We search for a **new** form of arrow composition $f \bullet g$ such that e.g.

 $(f \bullet g) = [2.0, -2.0, 1.414213562, -1.414213562]$

Output yields the square roots of the two natural numbers centered at 3.



Programming **f** • **g**:

 $f \bullet g a = concat [f b | b \leftarrow g a]$

where *concat* :: $[[a]] \rightarrow [a]$ concatenates a list of lists.

This works because, in Haskell, lists form a monad

 $\mathfrak{F} x = x^*$ is not only a functor but also a monad.

Our purpose in the slides to follow is to generalize $\mathfrak{F} x = x^*$ to other monads.

Remember that CT as a whole is based on two core notions:

- composition of arrows
- identity arrows.



So the way to go about the \mathfrak{F} -inflated arrows of (50) has to devise a form of composition and an identity.

For this we need a CT construction known as a **monad**:

Let \mathfrak{F} be an (endo)functor in some category \mathbb{C} , such that the following arrows always exist, for any X:

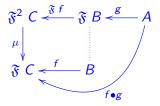
 $X \xrightarrow{\eta} \mathfrak{F} X \xleftarrow{\mu} \mathfrak{F}^2 X$

subject to a number of **properties** left out for the moment.

Why are such arrows useful?



They enable us to complete diagram (50),



where μ copes with the **nesting** of effects (exceptions on top of exceptions, for instance). The other arrow, $X \xrightarrow{\eta} \mathfrak{F} X$, converts a **pure** value into an effectful one.

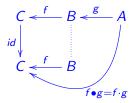
Thus $f \bullet g$ can be regarded as a form of (monadic) **composition**.



Indeed, the monadic properties (which we once again skip for brevity) grant the expected properties, with η behaving as identity:

 $f \bullet (g \bullet h) = (f \bullet g) \bullet h$ $f \bullet \eta = f = \eta \bullet f$

Now suppose $\mathfrak{F} X = X$, the identity functor:



Conclude that we have been working in a monad since the very beginning of this course — the **identity** monad!



A monad instance dear to functional programmers is the **list** monad :

 $\mu [] = []$ $\mu (l:t) = l + \mu t$

where $\mu = concat$ — list concatenation — and

 $\eta a = [a]$

builds singleton lists.

If we ignore the ordering of elements in a list, this monad mimics bounded **non-determinism**. See the next slide for an evolution of this idea.



The monad

$$X \xrightarrow{\eta} \mathfrak{P} X \xleftarrow{\mu} \mathfrak{P}^2 X$$

is *par excellence* the one behind non-deterministic finite automata (NFSA), where $\mathfrak{P} X = \{ S \mid S \subseteq X \}$. Its components are

 $\mu \{\} = \{\}$ $\mu (\{l\} \cup t) = l \cup \mu t$

- union of a set of sets - and

 $\eta x = \{x\}$

which builds singleton sets.



Here is a way of writing $f \bullet g$ in a (generic) pointwise manner

 $(f \bullet g) a = \mathbf{do} \{ b \leftarrow g a; return (f b) \}$

where *return* is a synonym for η popular in monadic languages such as e.g. Haskell.

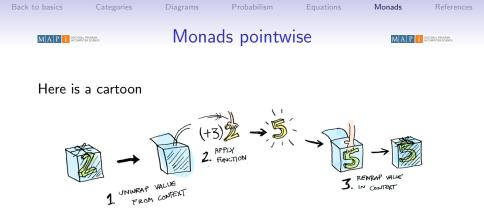
Likewise,

do { $a \leftarrow x$; return (g a) }

denotes the application of $A \xrightarrow{g} \mathfrak{F} B$ to monadic data x.

A final example: **do** { $a \leftarrow x$; $b \leftarrow y$; return (x + y) } adds two numbers extracted from monadic data.

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for the calculation of $\mathfrak{F}(+3) \times$, where x = return 2 is the monadic object which contains number 2 in monad \mathfrak{F} :

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do { $a \leftarrow return 2; return (a + 3) }$



We observe that properties

 $f \bullet (g \bullet h) = (f \bullet g) \bullet h$ $f \bullet \eta = f = \eta \bullet f$

where

 $f \bullet g = \mu \cdot (\mathfrak{F} f) \cdot g$

offer a sub-category of \mathbb{C} , that made of \mathfrak{F} -inflated arrows only, that is, homsets of pattern $\mathbb{C}(A, \mathfrak{F} B)$.

Such a sub-category (usually denoted by \mathbb{C}^{\flat}) is known as the **Kleisli** category associated to monad \mathfrak{F} in \mathbb{C} , as follows:

 $\mathbb{C}^{\flat}(A,B) \cong \mathbb{C}(A,\mathfrak{F}B)$



The best known example of a Kleisli category is $\mathbb{R} = \mathbb{S}^{\flat}$, induced by monad \mathfrak{P} :

 $\mathbb{R}(A,B) \cong \mathbb{S}(A,\mathfrak{P}B)$

This simply tells that every **relation** can be represented by a **set**-valued function.

It can also be shown that \mathbb{M} and \mathbb{P} can be regarded as Kleisli categories of suitable **monads** in \mathbb{S} .

This is why S is, for many people, "the category par excellence".



The application of the two **CT** concepts of **functor** and **monad** to **programming** is perhaps the most significant development in the software sciences for the last 30 years.

To program with them one needs to know about **CT**, the **lingua franca** of software science.

Many useful monads can be found in the literature.

Haskell is among the languages that first incorporated ${\rm functors}$ and ${\rm monads}$ into themm.^2

Python, Scala, Swift, F# have got there too; Java8 seems to have tried.

²See e.g. https://hackage.haskell.org/package/base-4.9.0.0/docs/ Control-Monad.html.





Equations

Monads

References



Postlude

Sir Arthur Eddington (1882-1944):

"I cannot believe that anything so ugly as multiplication of matrices is an essential part of the scheme of nature"

(in "Relativity Theory of Electrons and Protons", 1936).



Serious warning to mathematicians and physicists — **notations** should be **elegant** :-)

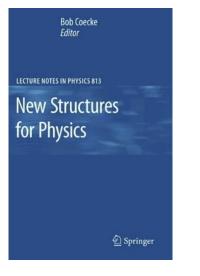
I agree — standard **linear algebra notation** is clumsy by **modern computer science** standards.



Unfortunately, Sir A. Eddington did not live long enough to find the following answer to his complaint,

> "New Structures for Physics", Lect. Notes in Physics volume 813

compiled by B. Coecke.

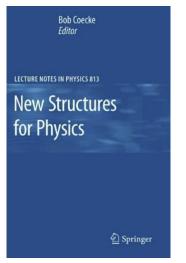


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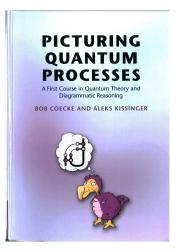
The generic structures (monoidal categories) in which **quantum physics** are expressed in this book generalize the categories \mathbb{R} and \mathbb{P} that we have studied in this module.



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More recently, a quite accessible book by B. Coecke and Aleks Kissinger:



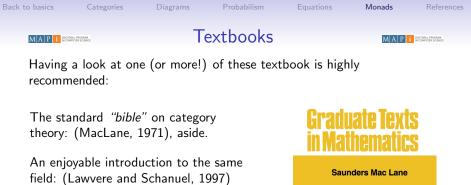
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This **unified way** of thinking has been a subject of research at the HASLab (INESC TEC & U.Minho) laboratory for quite a while, covering **application areas** as disparate as e.g.

- Data mining (Macedo and Oliveira, 2015; Oliveira and Macedo, 2017)
- **Component-oriented** programming (Oliveira and Miraldo, 2016)

- Fault propagation (Oliveira, 2012)
- Managing risk in functional programming (Murta and Oliveira, 2015)
- Weighted automata (Oliveira, 2013)
- Linear algebra (Macedo and Oliveira, 2013)



Another good book for computer scientists: (Pierce, 1991)

The standard "algebra of programming" textbook: (Bird and de Moor, 1997)

Categories for the Working Mathematician Second Edition

Springer

(There is much more on the web — just search for "Category Theory textbook").



References

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agrams

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quations

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